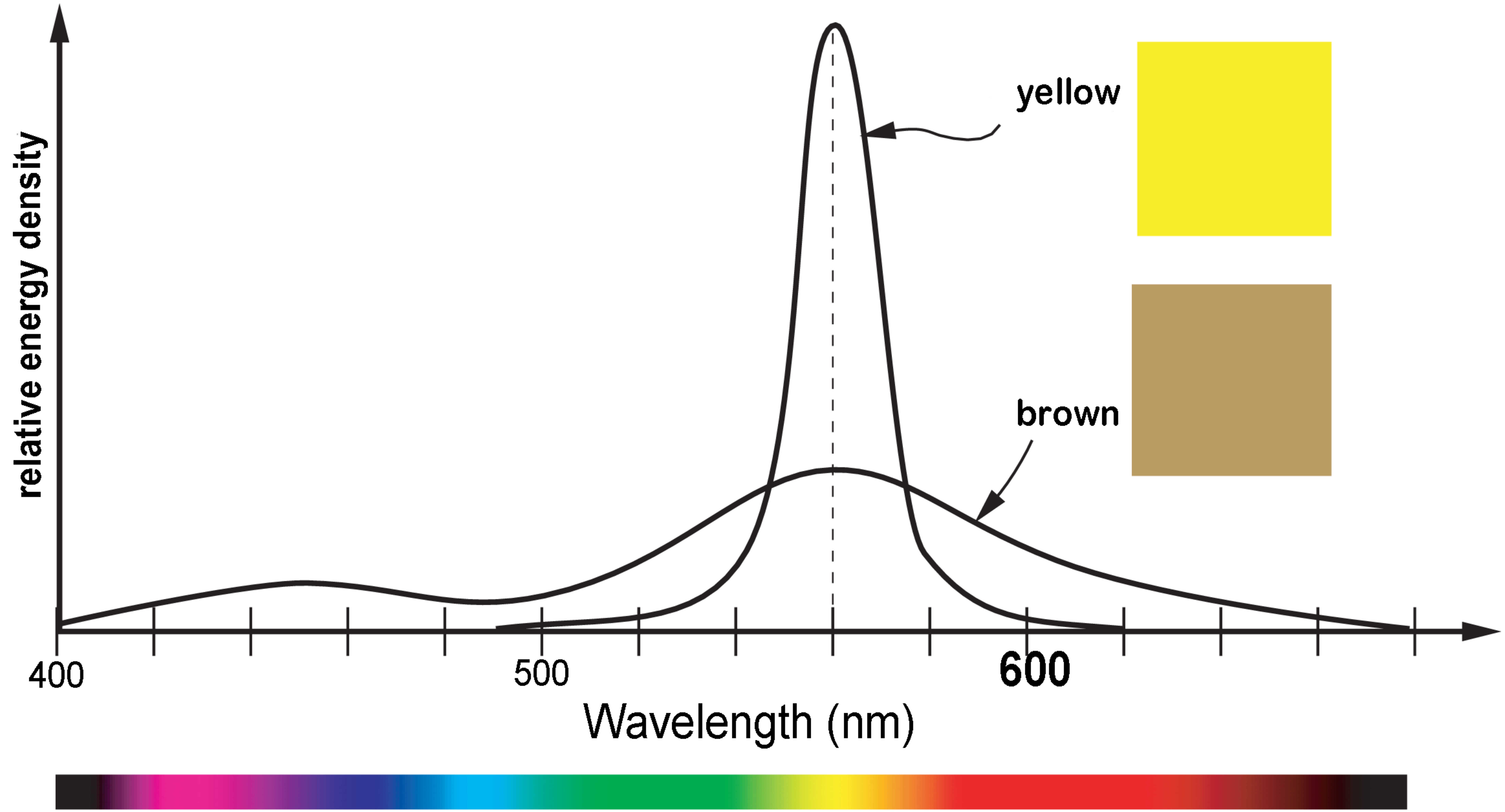
Data Visualization (CSCI 627/490)

Colormaps

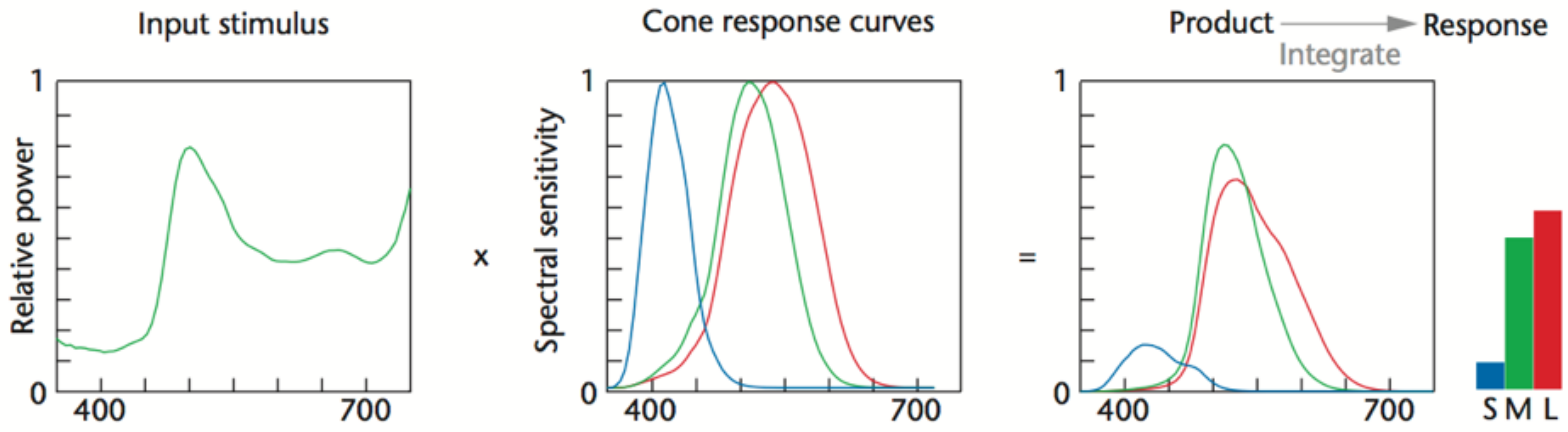
Dr. David Koop

Color != Wavelength



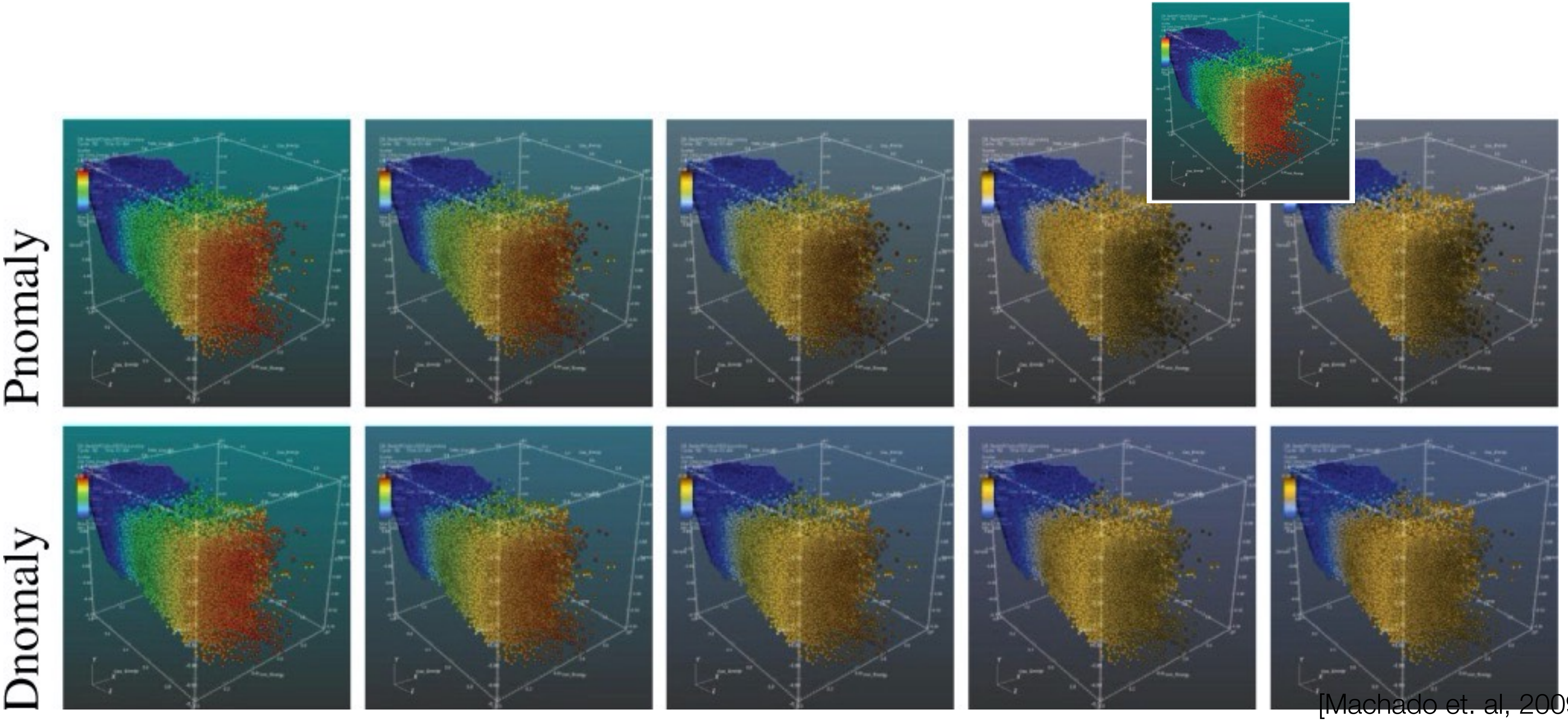
[via M. Meyer]

Human Color Perception



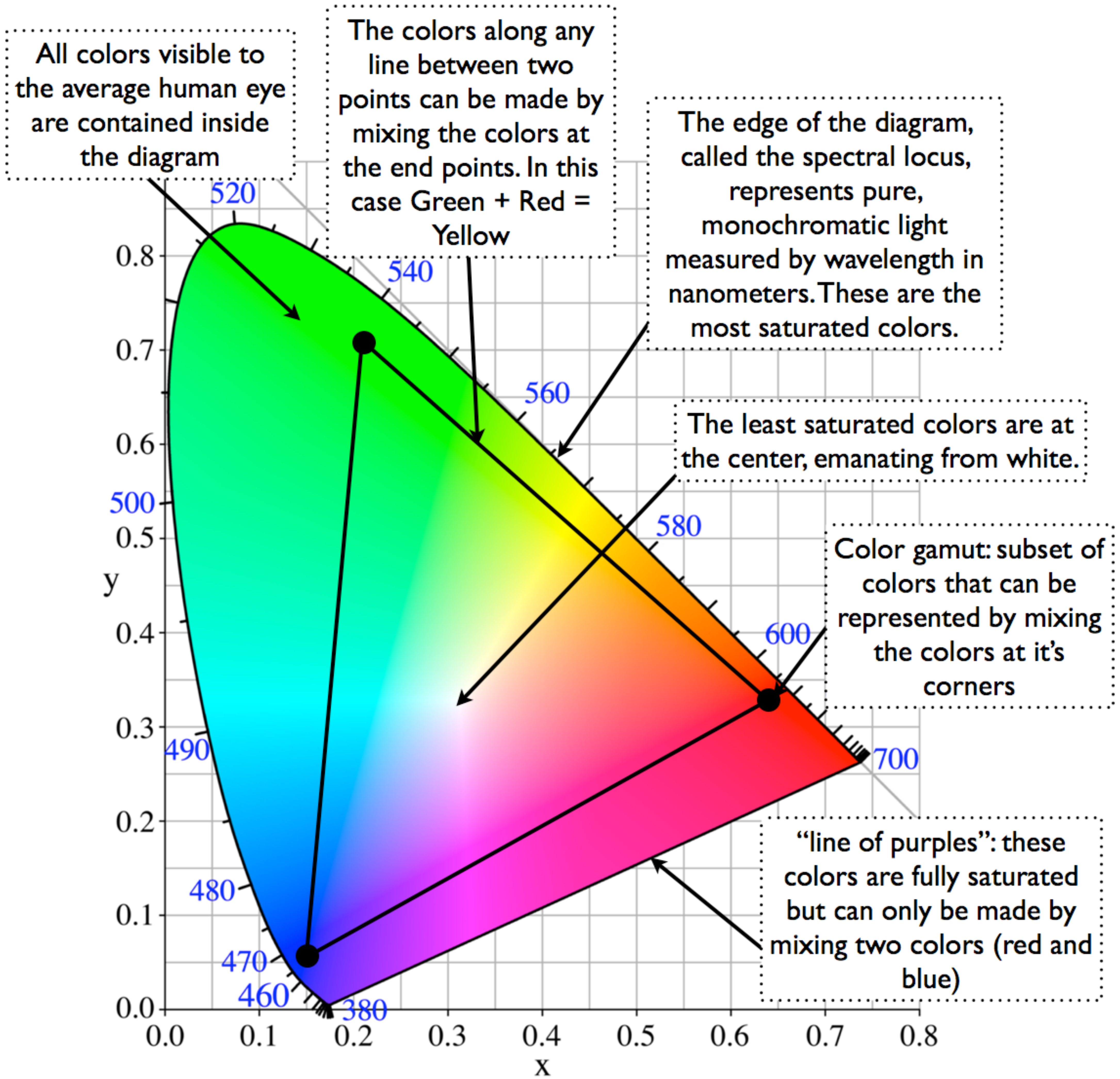
[via M. Meyer]

Simulating Color Blindness



[Machado et. al, 2009]

Color Spaces and Gamuts

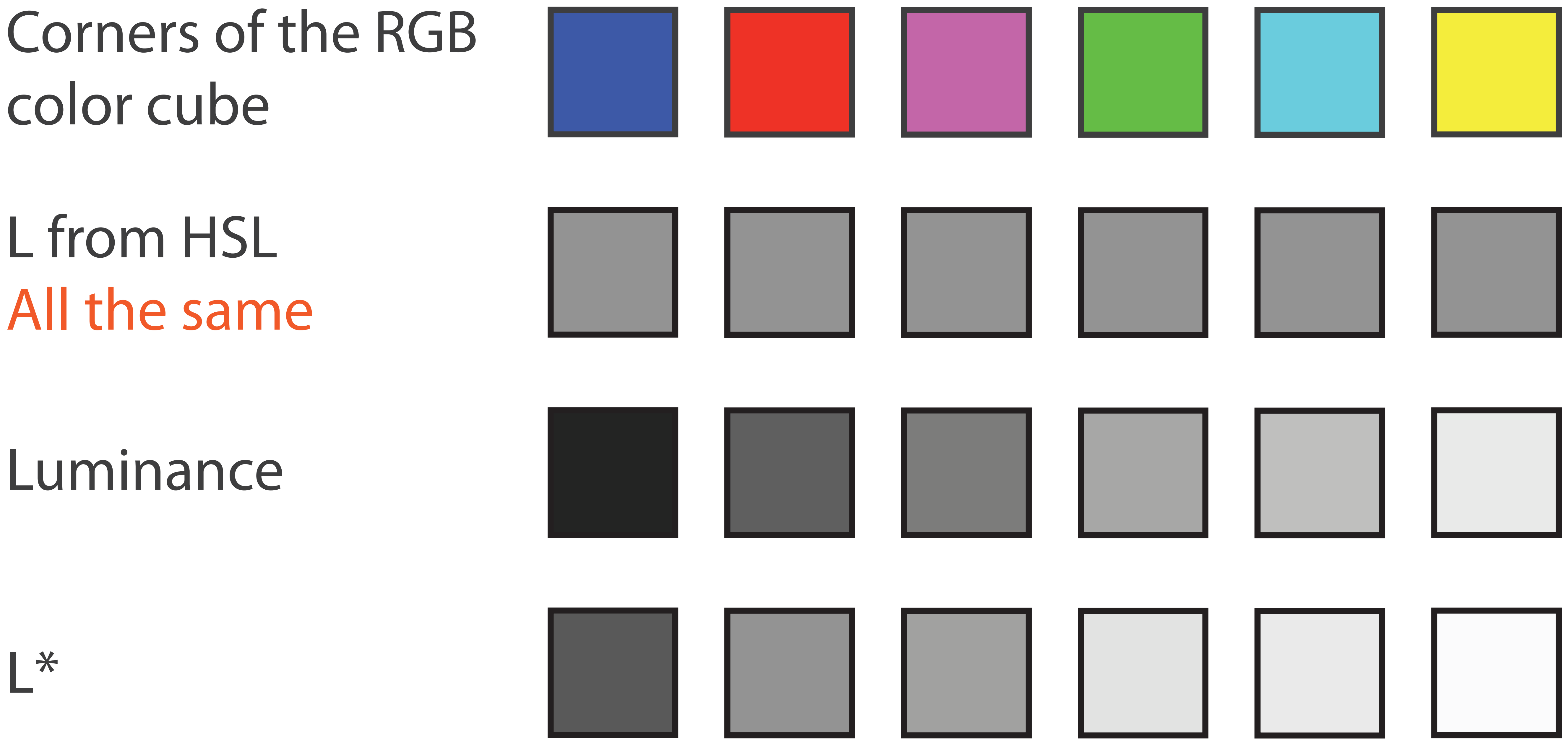


[Anatomy of a CIE Chromaticity Diagram]

- **Color space**: the organization of all colors in space
  - Often human-specific, what we can see (e.g. CIELAB)
- **Color gamut**: a subset of colors
  - Defined by corners of color space
  - What can be produced on a monitor (e.g. using RGB)
  - What can be produced on a printer (e.g. using CMYK)
  - The gamut of your monitor != the gamut of someone else's or a printer

Luminance

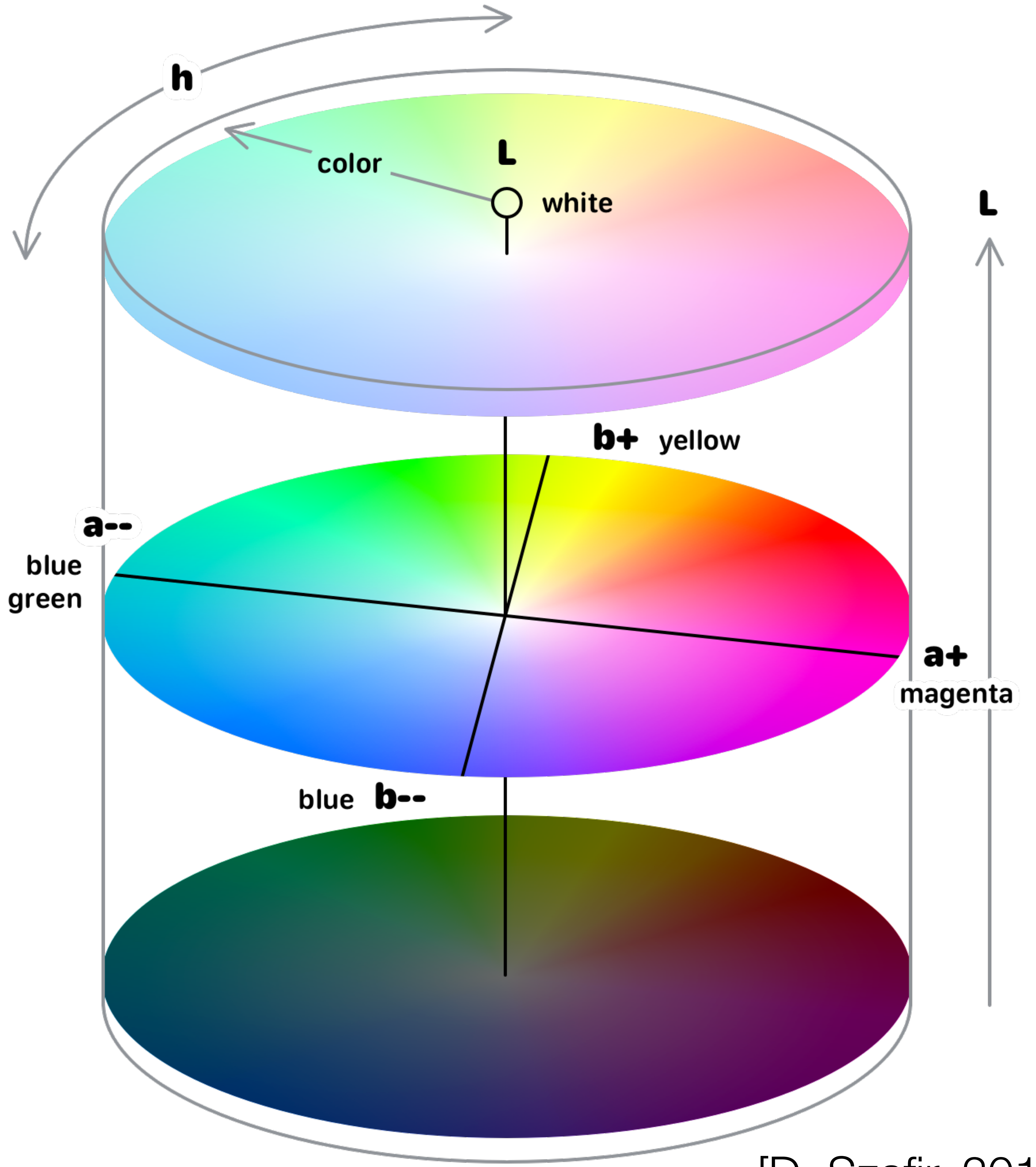
- HSL does not truly reflect the way we perceive color
- Even though colors have the same lightness, we perceive their luminance differently
- Our perception (L*) is **nonlinear**



[Munzner (ill. Maguire), 2014 (based on Stone, 2006)]

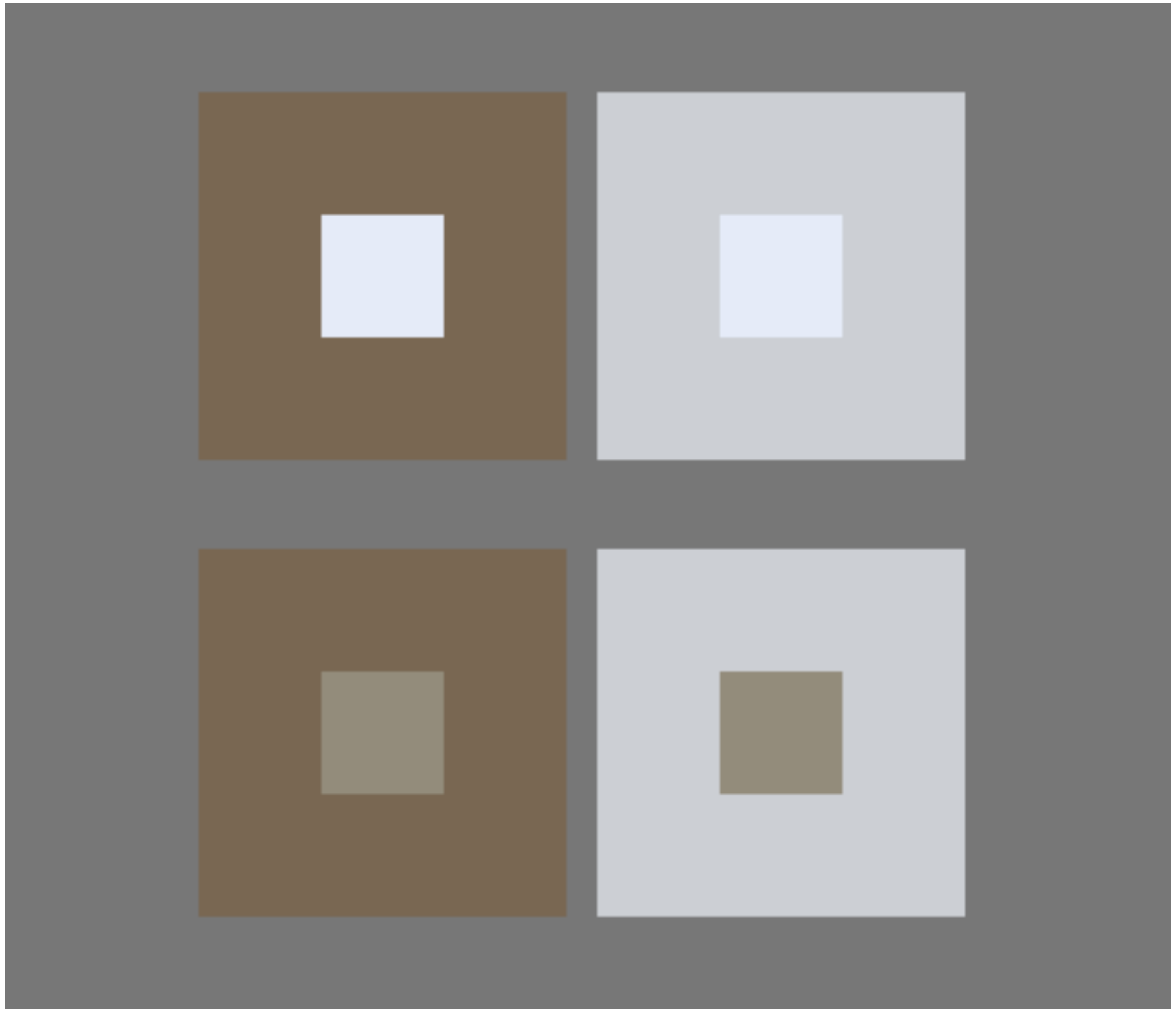
Violations of CIELAB Assumptions

- CIELAB:
  - Approximately perceptually linear
  - 1 unit of Euclidean distance = 1 Just Noticeable Difference (JND)
  - JND: people detect change at least 50% of the time
- Assumptions CIELAB makes:
  - Simple world
  - Isolation
  - Geometric



[D. Szafir, 2017]

Simultaneous Contrast



Midterm

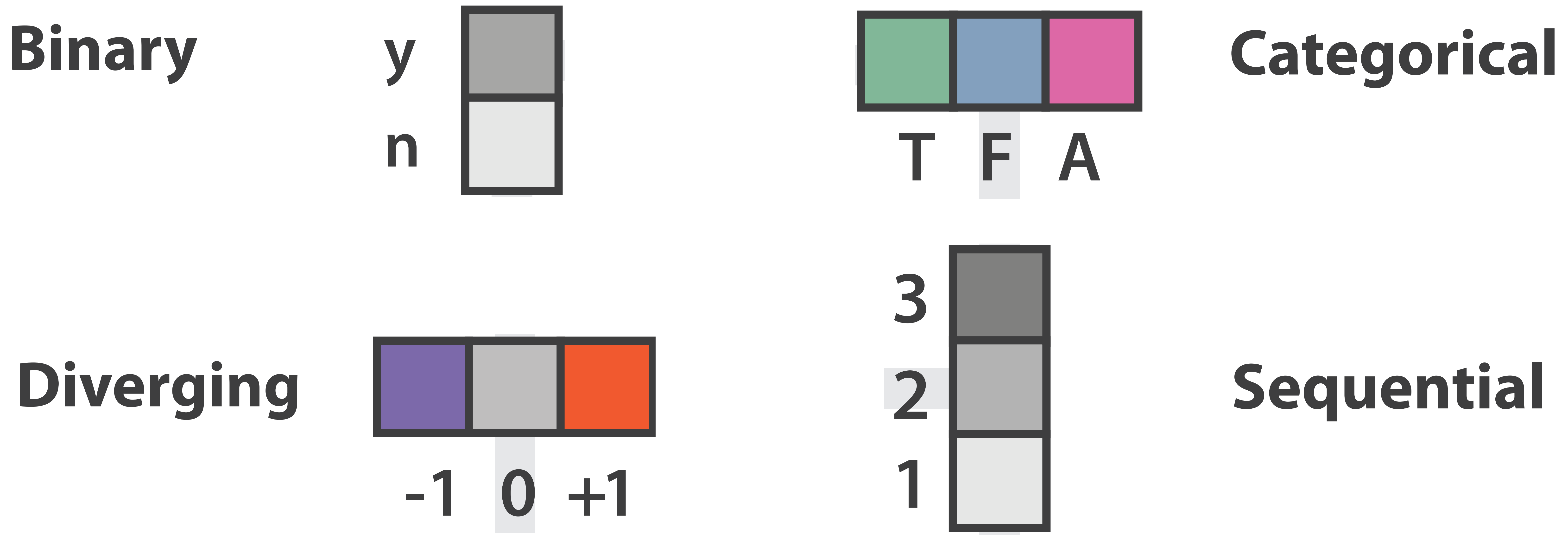
- Thursday, October 15
- Covers material through this week
- Format:
  - Multiple Choice
  - Free Response (often multi-part)
  - CS 627 students will have extra questions related to the research papers discussed

Project

- Two Possibilities:
  - Create an interactive visualization
  - Work on a research project
- Will be posting dataset choices

Colormap

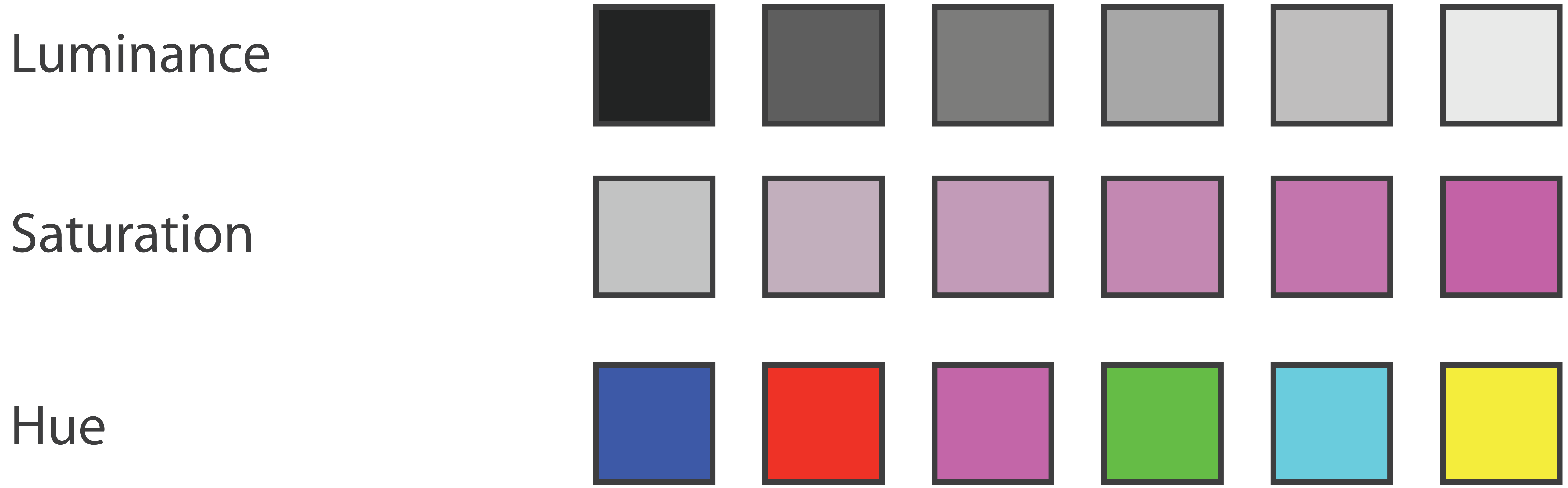
- A colormap specifies a mapping between colors and data values
- Colormap should follow the expressiveness principle
- Types of colormaps:



[Munzner (ill. Maguire), 2014]

Categorical vs. Ordered

- Hue has no implicit ordering: use for categorical data
- Saturation and luminance do: use for ordered data

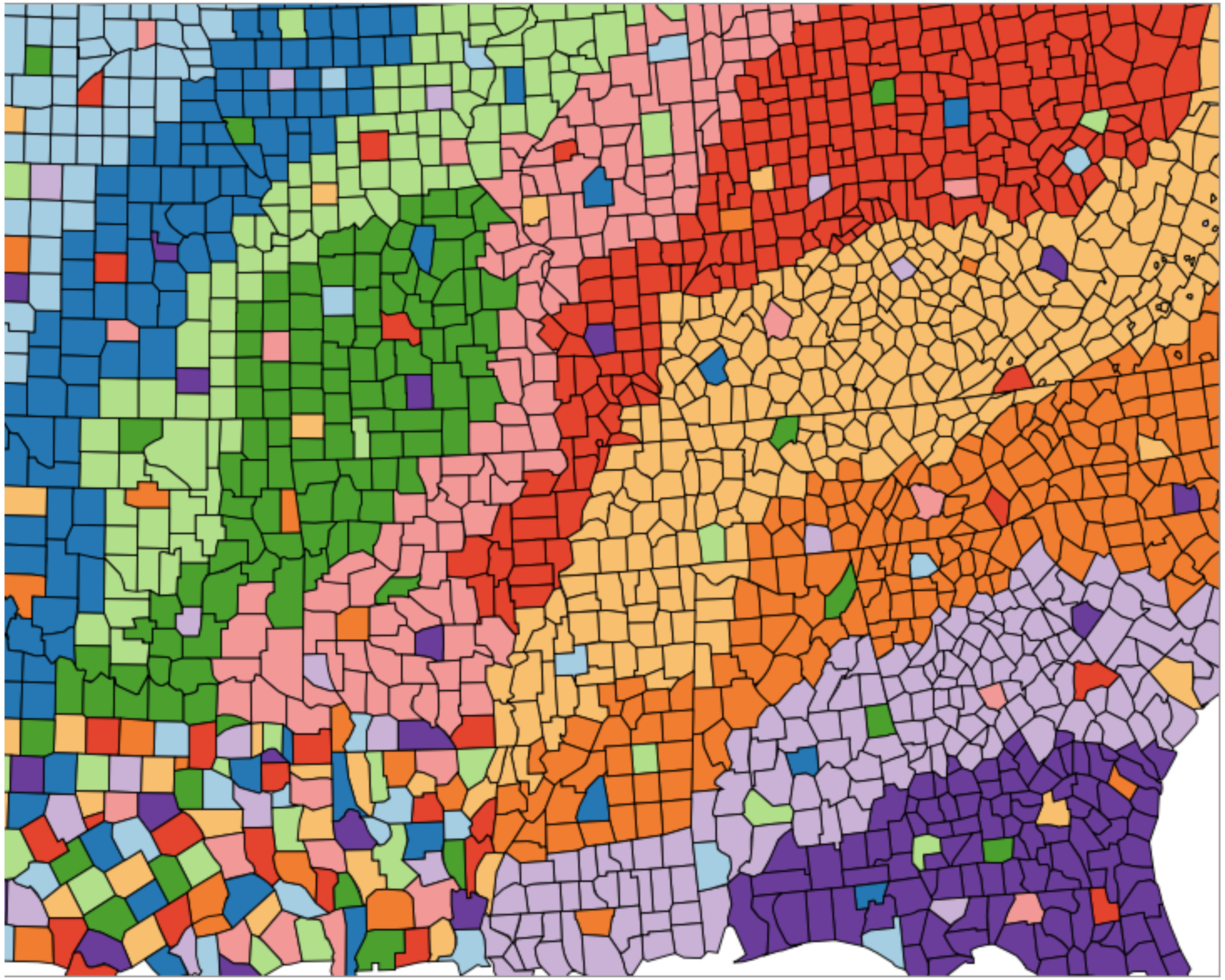


[Munzner (ill. Maguire), 2014]

Categorical Colormap Guidelines

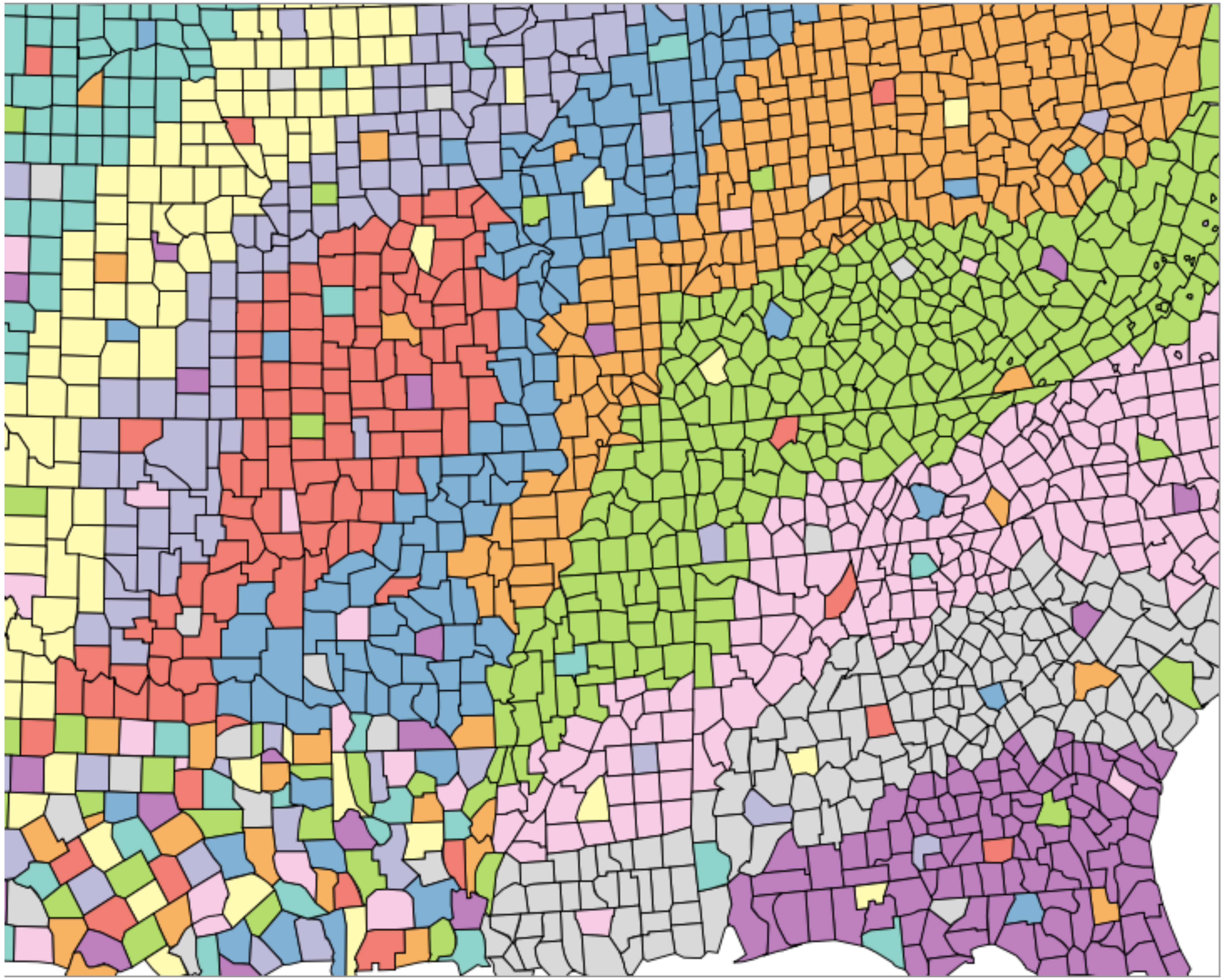
- Don't use too many colors (~12)
- Remember your background has a color, too
- Nameable colors help
- Be aware of luminance (e.g. difference between blue and yellow)
- Think about other marks you might wish to use in the visualization

Categorical Colormaps



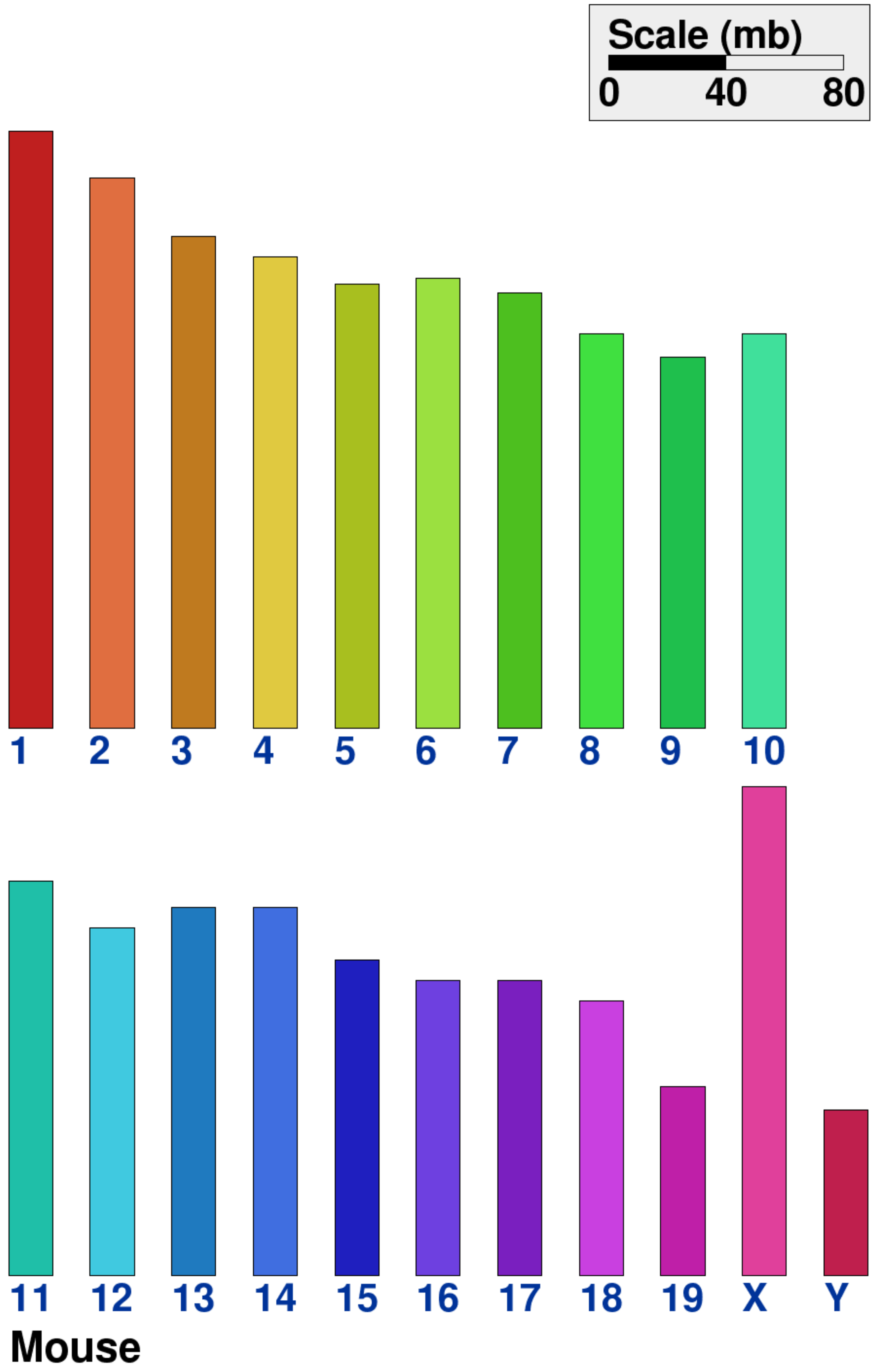
[colorbrewer2.org]

Categorical Colormaps



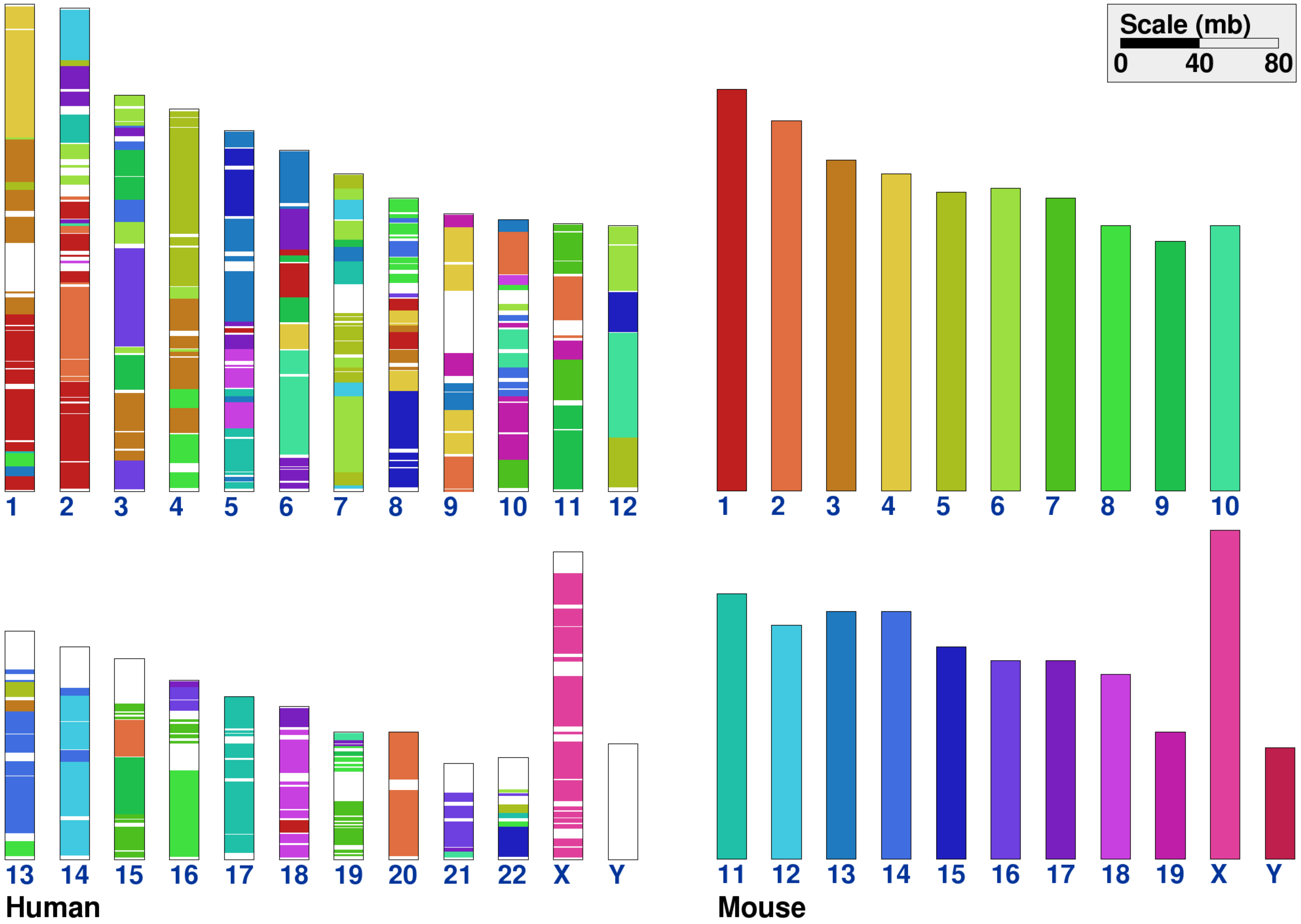
[colorbrewer2.org]

Number of distinguishable colors?



[Sinha & Meller, 2007]

Number of distinguishable colors?



[Sinha & Meller, 2007]

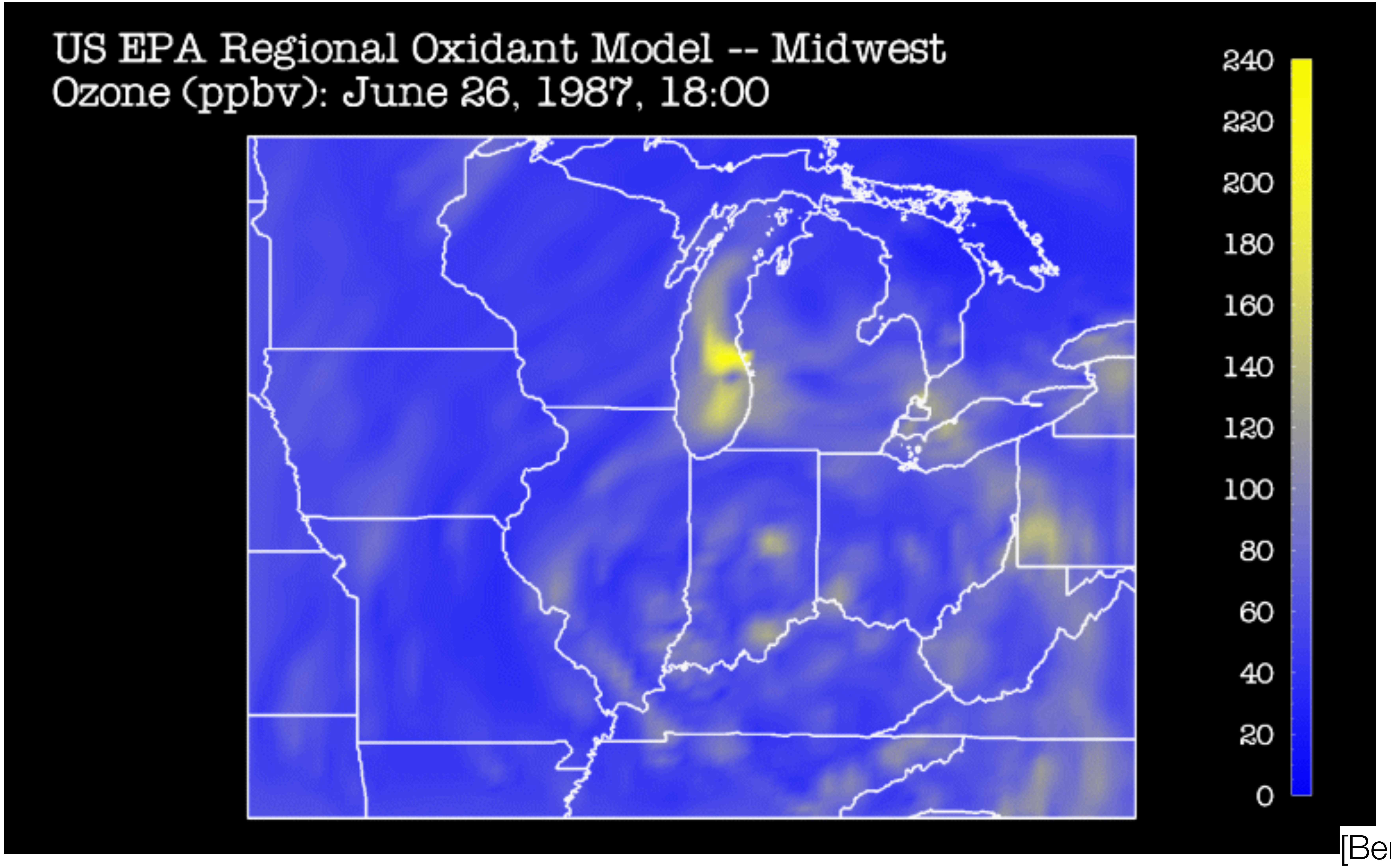
Discriminability

- Often, fewer colors are better
- Don't let viewers combine colors because they can't tell the difference
- Make the combinations yourself
- Also, can use the "Other" category to reduce the number of colors

Ordered Colormaps

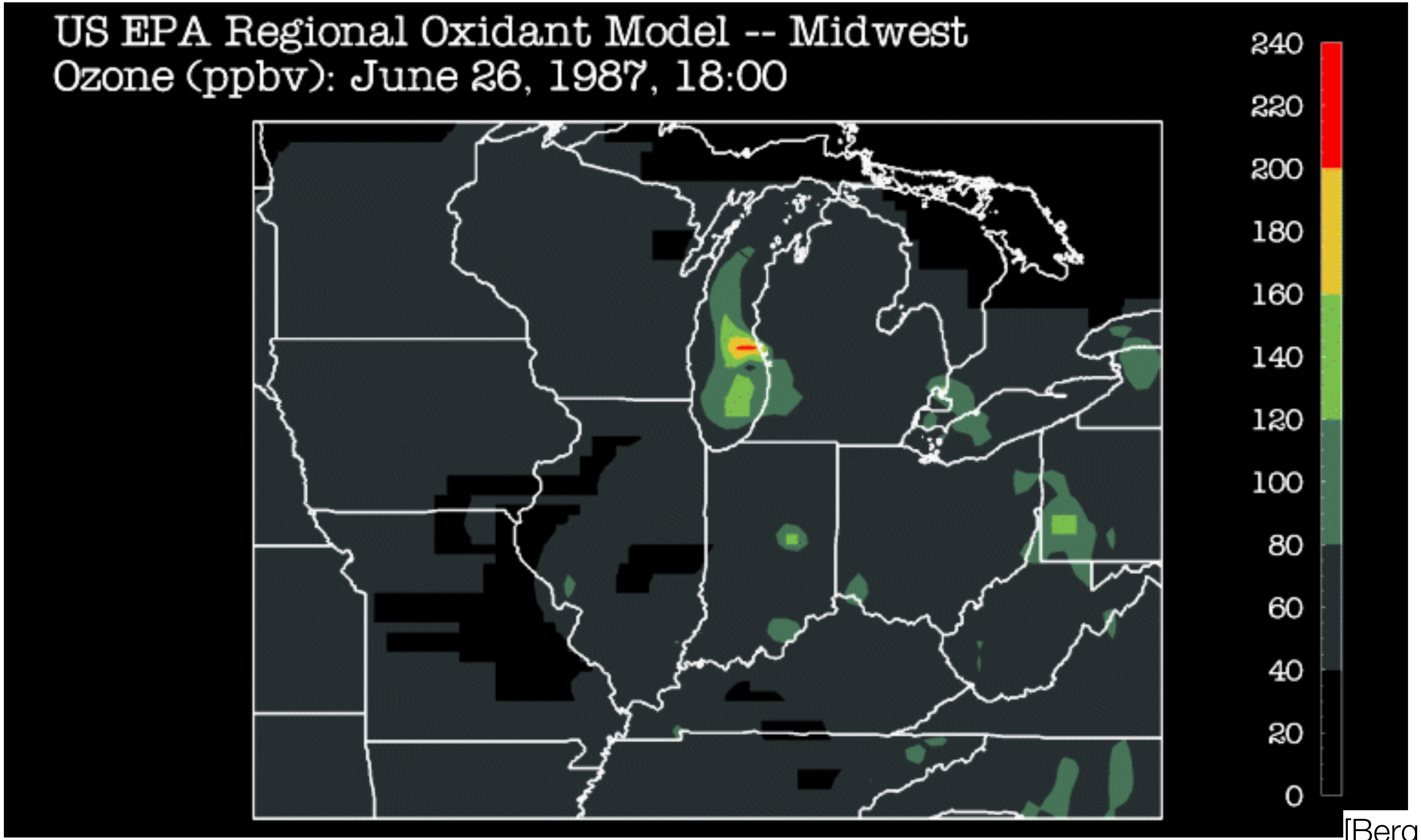
- Used for ordinal or quantitative attributes
- [0, N]: Sequential
- [-N, 0, N]: Diverging (has some meaningful midpoint)
- Can use hue, saturation, and luminance
- Remember hue is not a magnitude channel so be careful
- Can be **continuous** (smooth) or **segmented** (sharp boundaries)
  - Segmented matches with ordinal attributes
  - Can be used with quantitative data, too.

Continuous Colormap



[Bergman et al., 1995]

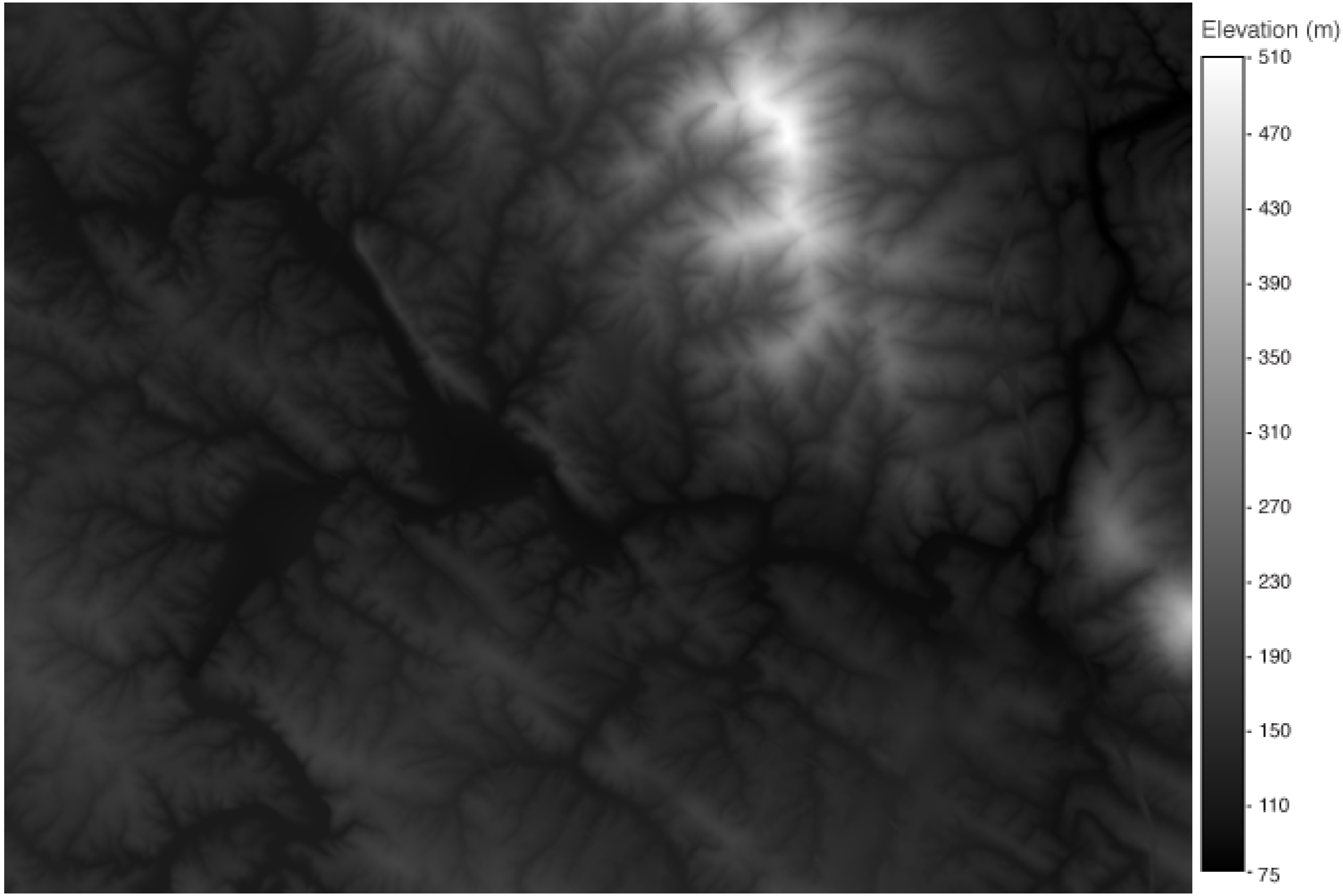
Segmented Colormap



[Bergman et al., 1995]

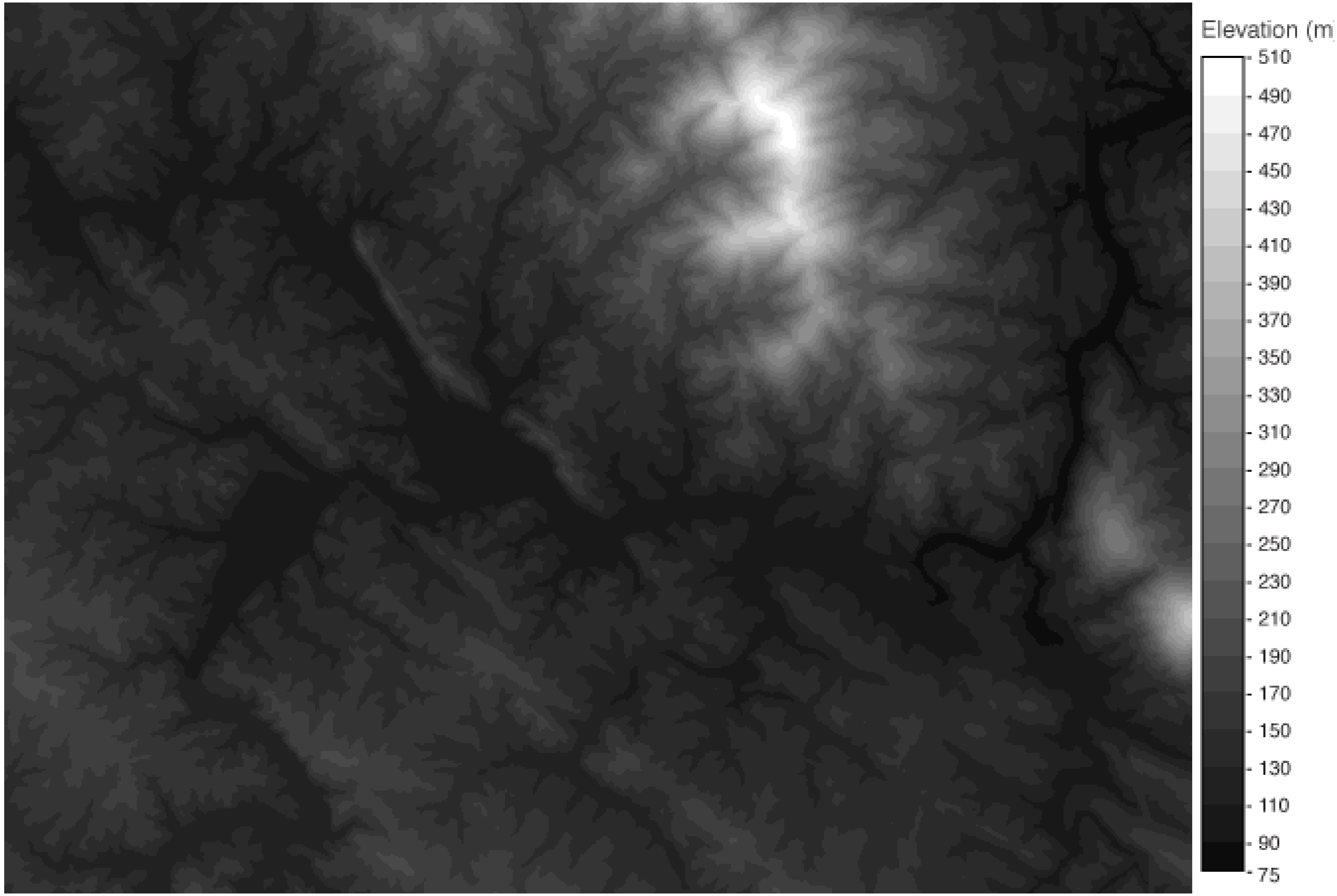
Is continuous better than segmented?

Continuous



[Padilla et al., 2017]

Many Segments



[Padilla et al., 2017]

Fewer Segments

[Padilla et al., 2017]

Types of Tasks

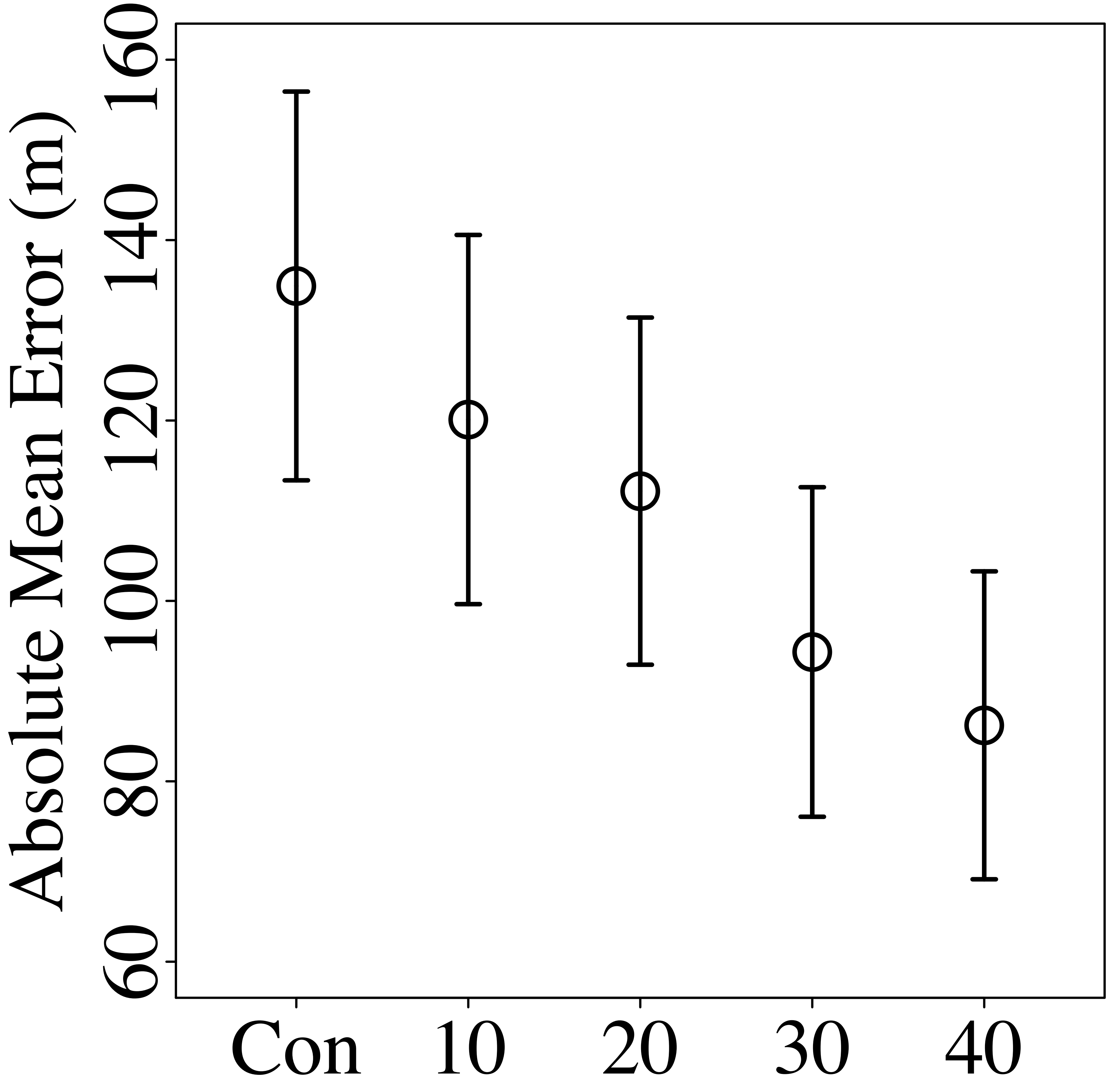
- Locate/Explore & Identify: Highest Point (Global, In Region), 275m
- Locate/Explore & Compare: Height Compare/Rank
- Explore & Identify: Steepest
- Lookup & Identify: Lookup
- Explore & Compare: Steepness Compare/Rank
- Browse & Summarize: Average Height
- Browse & Compare: Compare Average Height
- Combination: Steepest at 355m

[Padilla et al., 2017]

Results

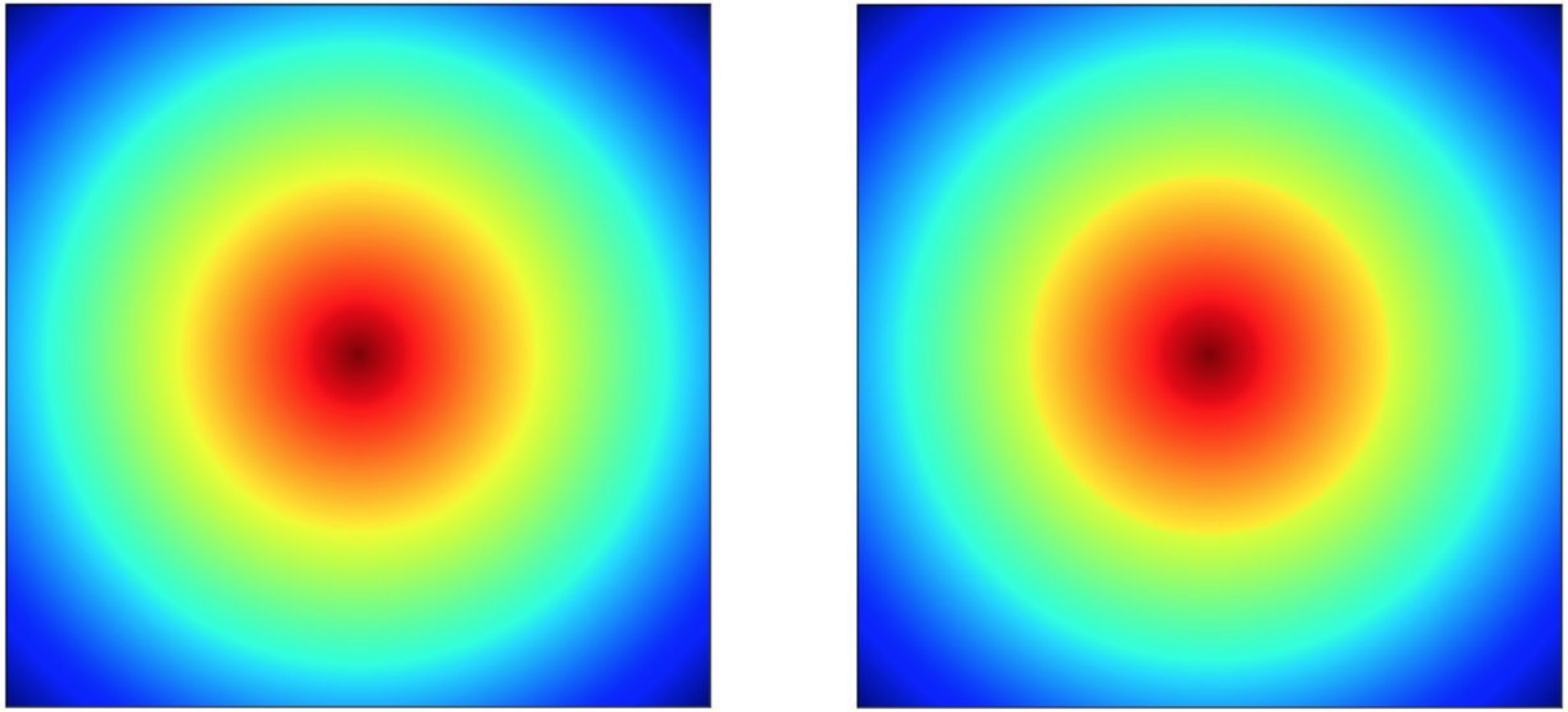
- "[C]ontrary to the expressiveness principle, no cases were found in which a continuous encoding of 2D scalar field data was advantageous for task accuracy, and for some tasks, specific binned encodings facilitated accuracy."
- "[S]upport for the counterintuitive finding that decisions with binned encoding were slower than those made with continuous encoding"
- Word of caution: single image!

Lookup Task (Lower)



[Padilla et al., 2017]

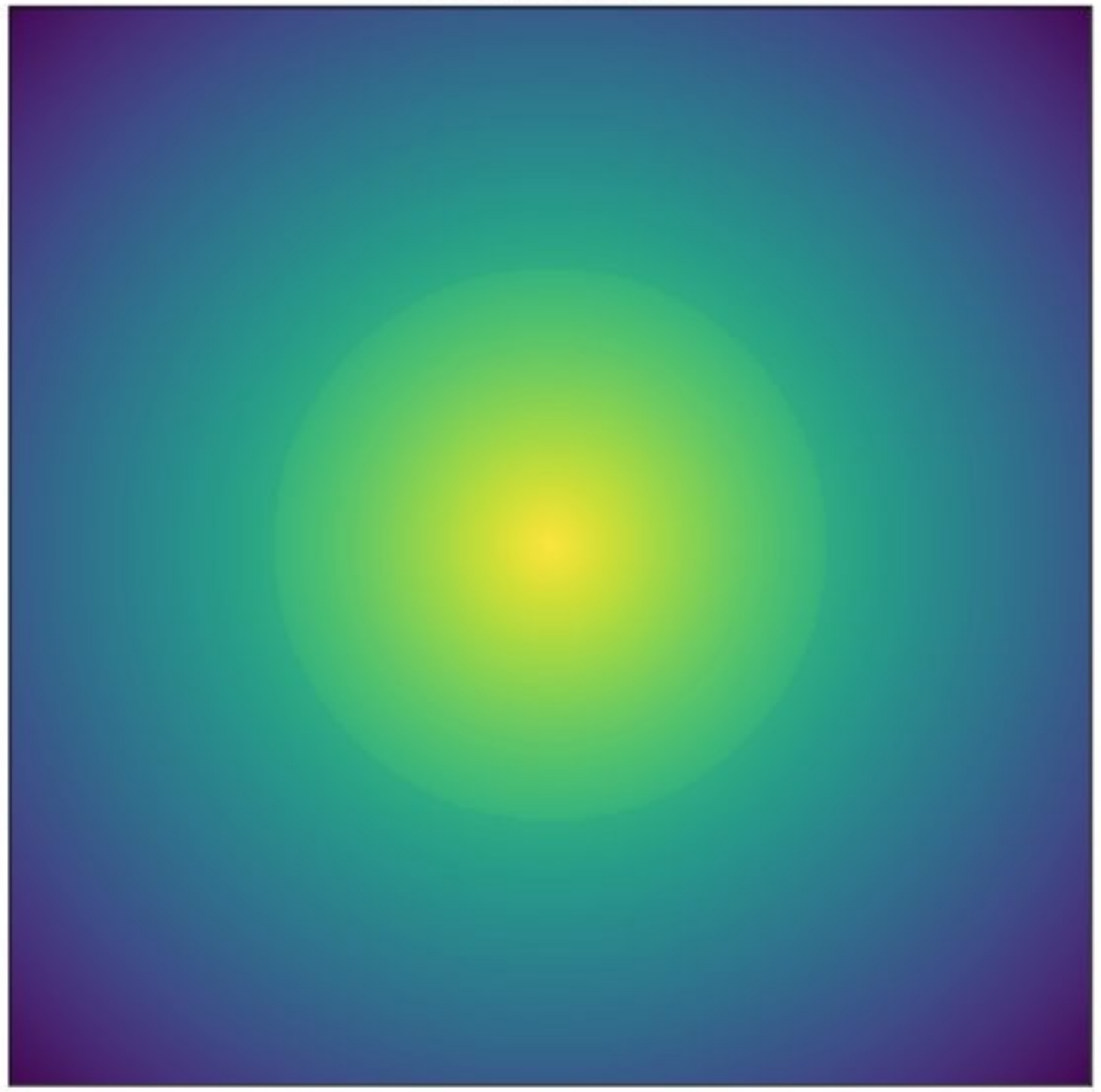
Don't Use Rainbow Colormaps

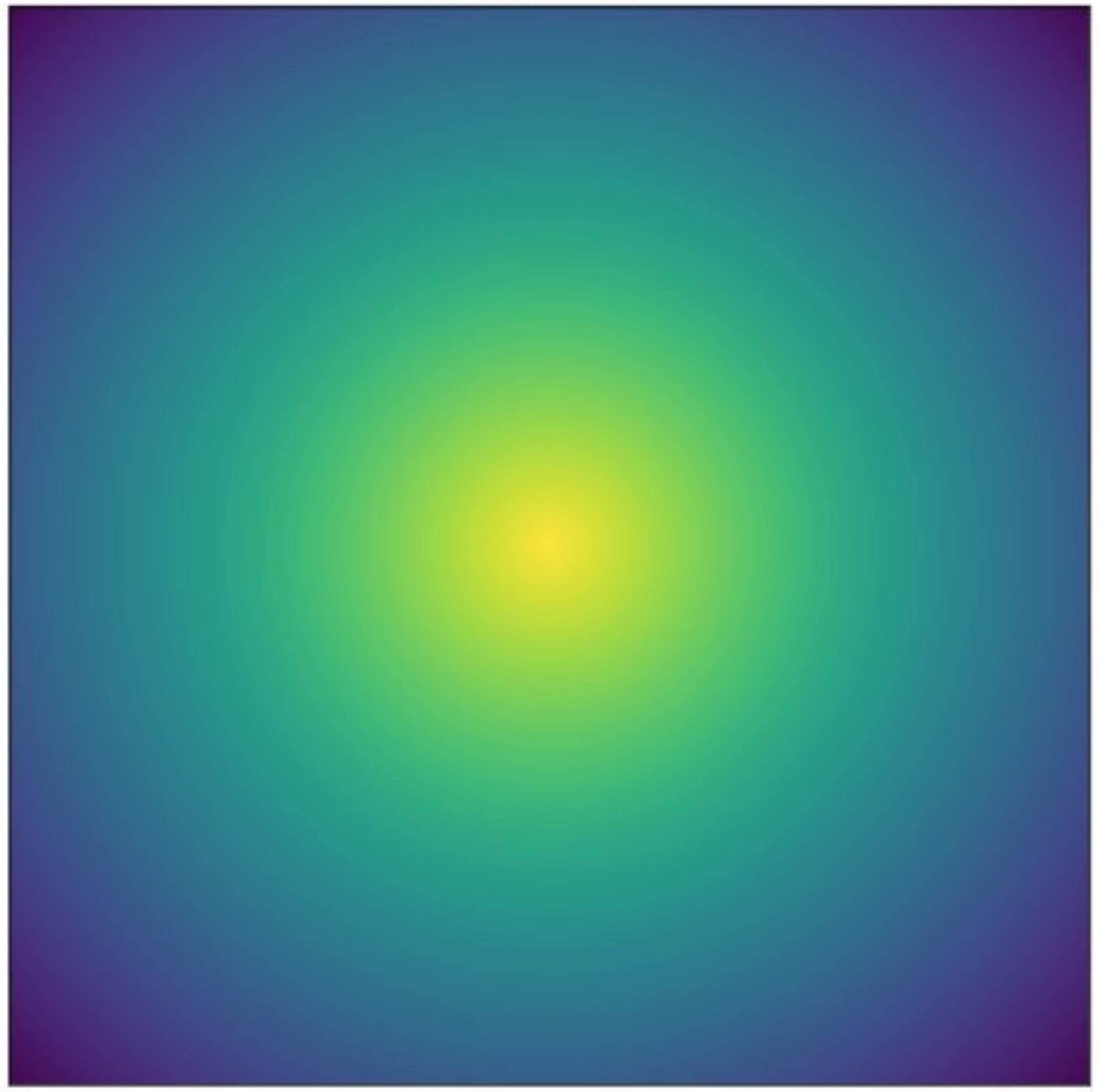


Which has a discontinuity?

[M. Bussonnier]

Other Colormaps Work Better

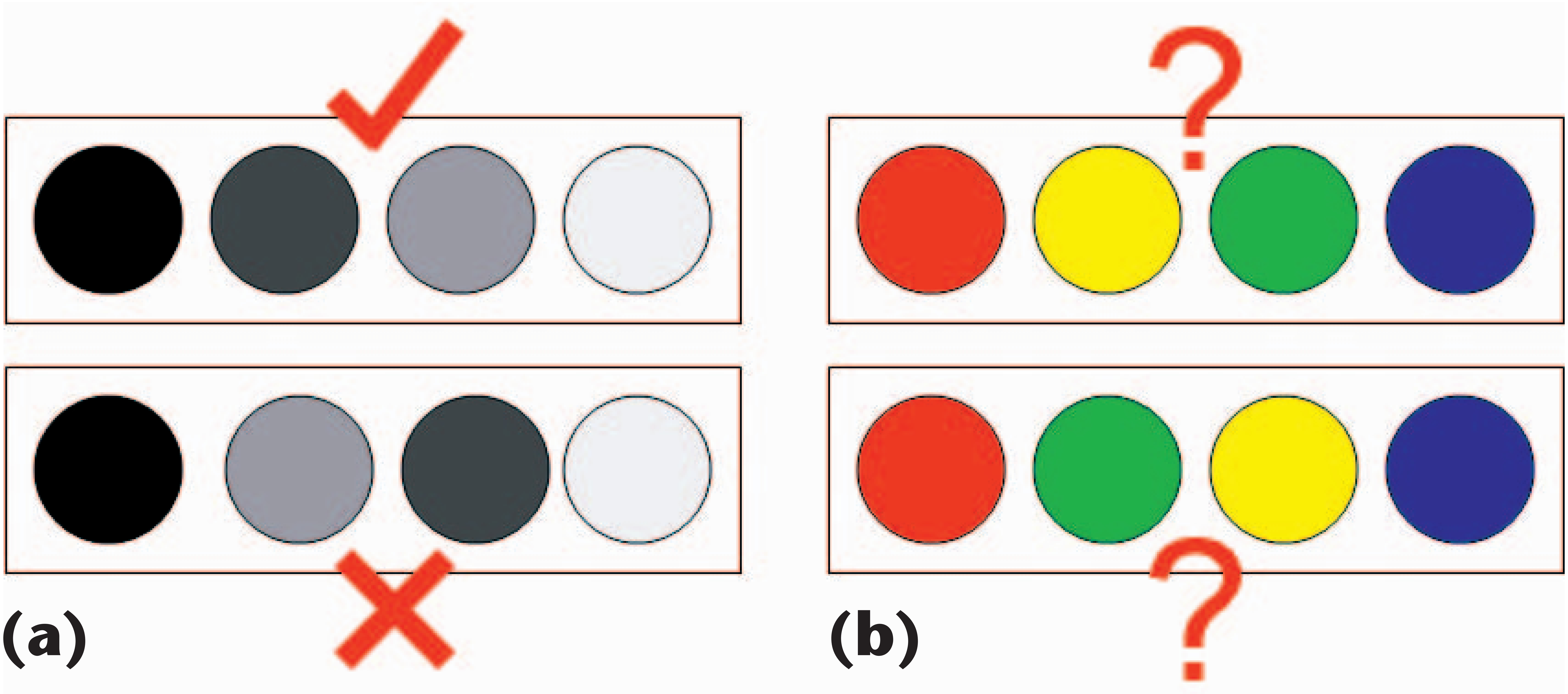




Which has a discontinuity?

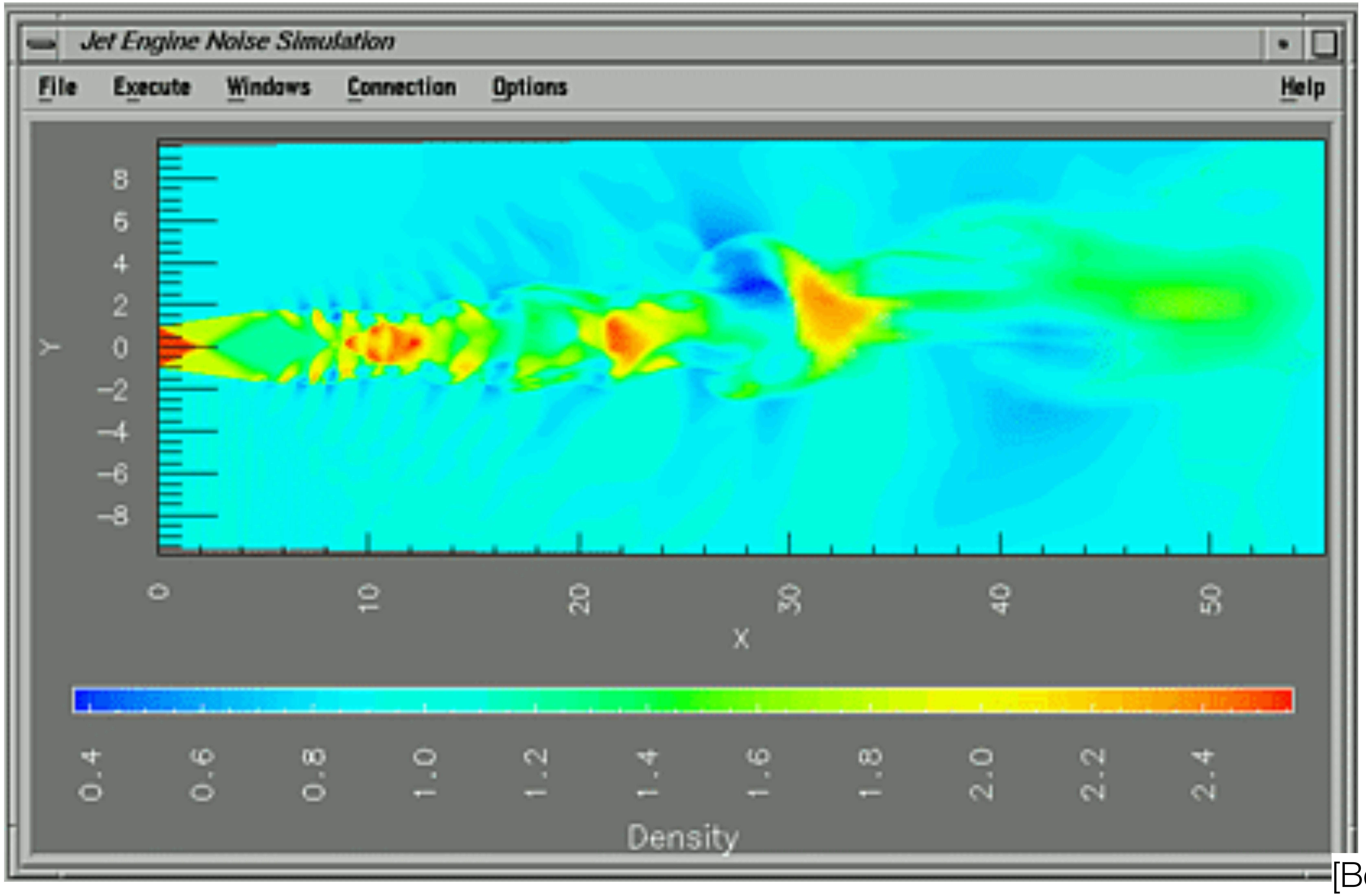
[M. Bussonnier]

Ordering Color?



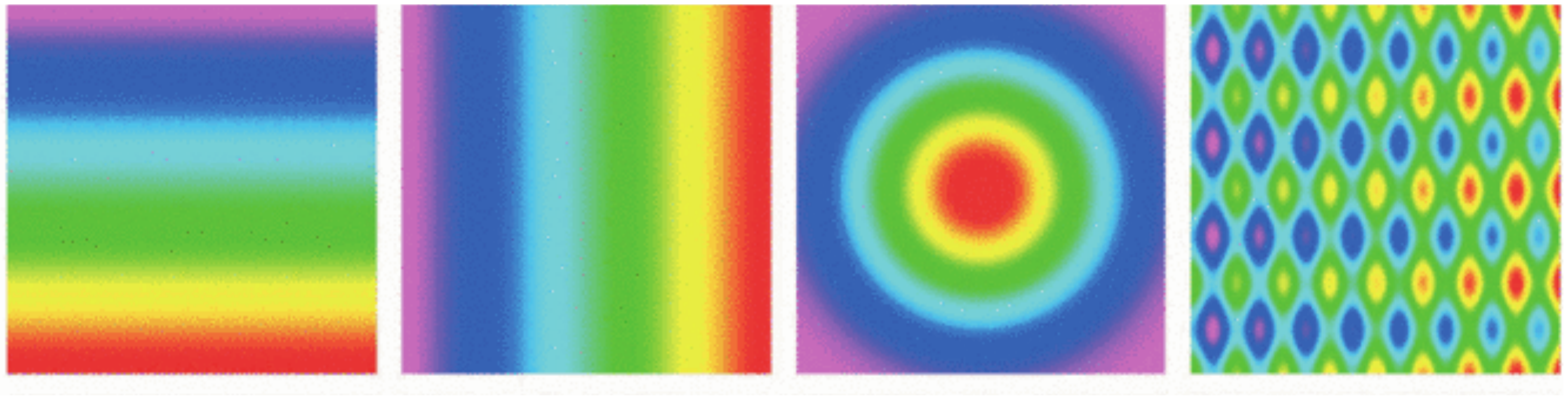
[Borland & Taylor, 2007]

Rainbow Colormap



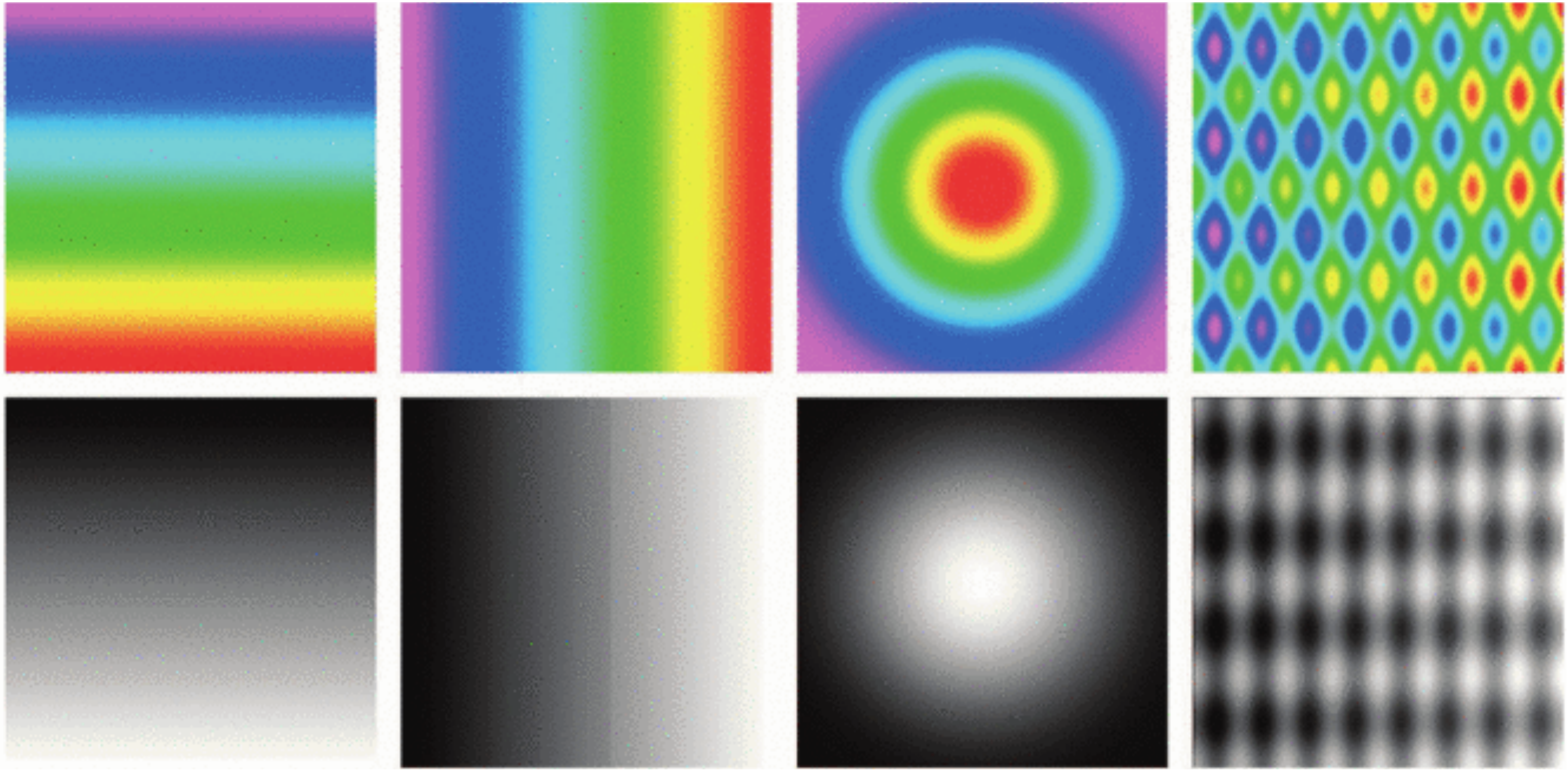
[Bergman et al., 1995]

Artifacts from Rainbow Colormaps



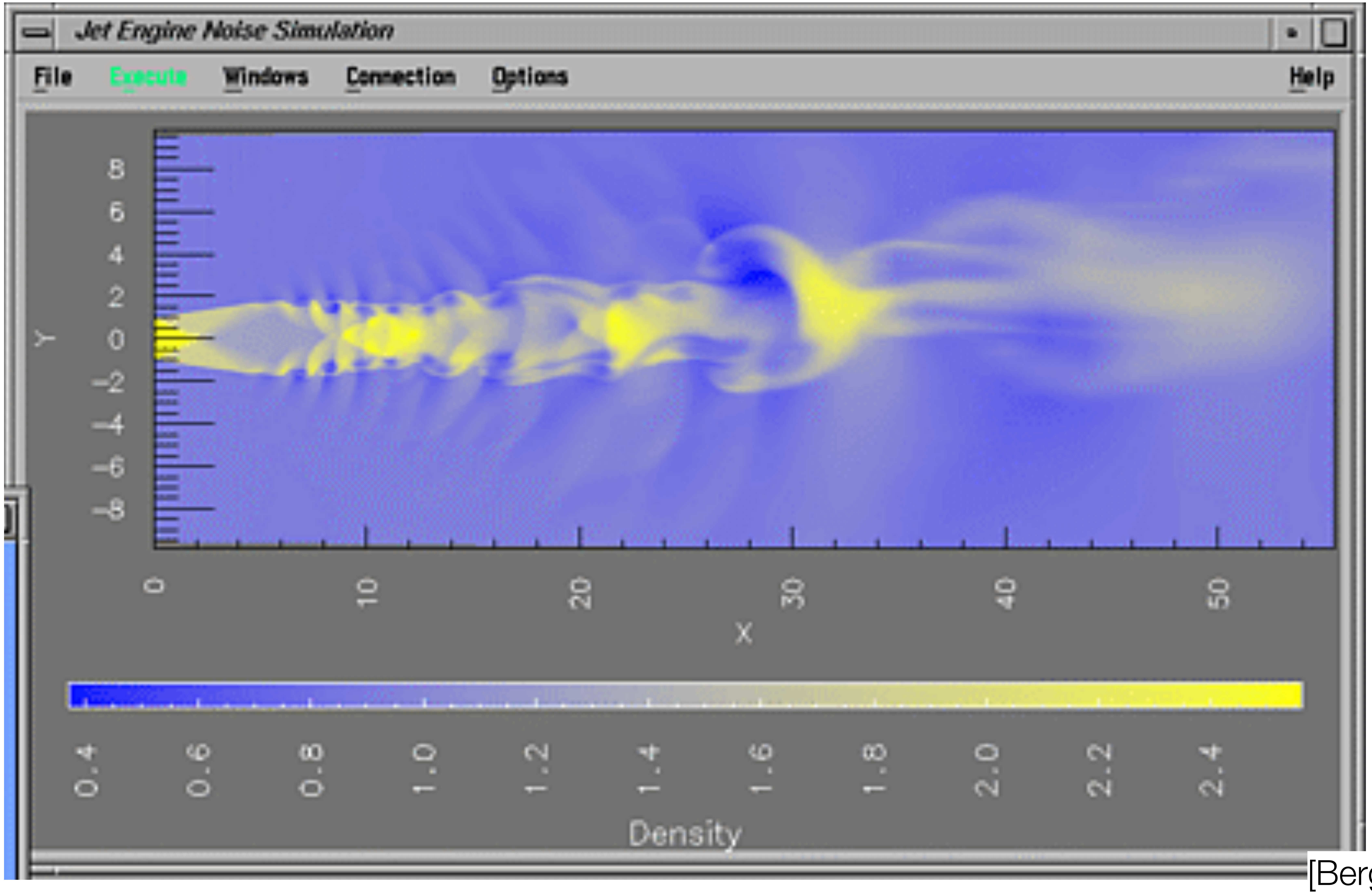
[Borland & Taylor, 2007]

Artifacts from Rainbow Colormaps



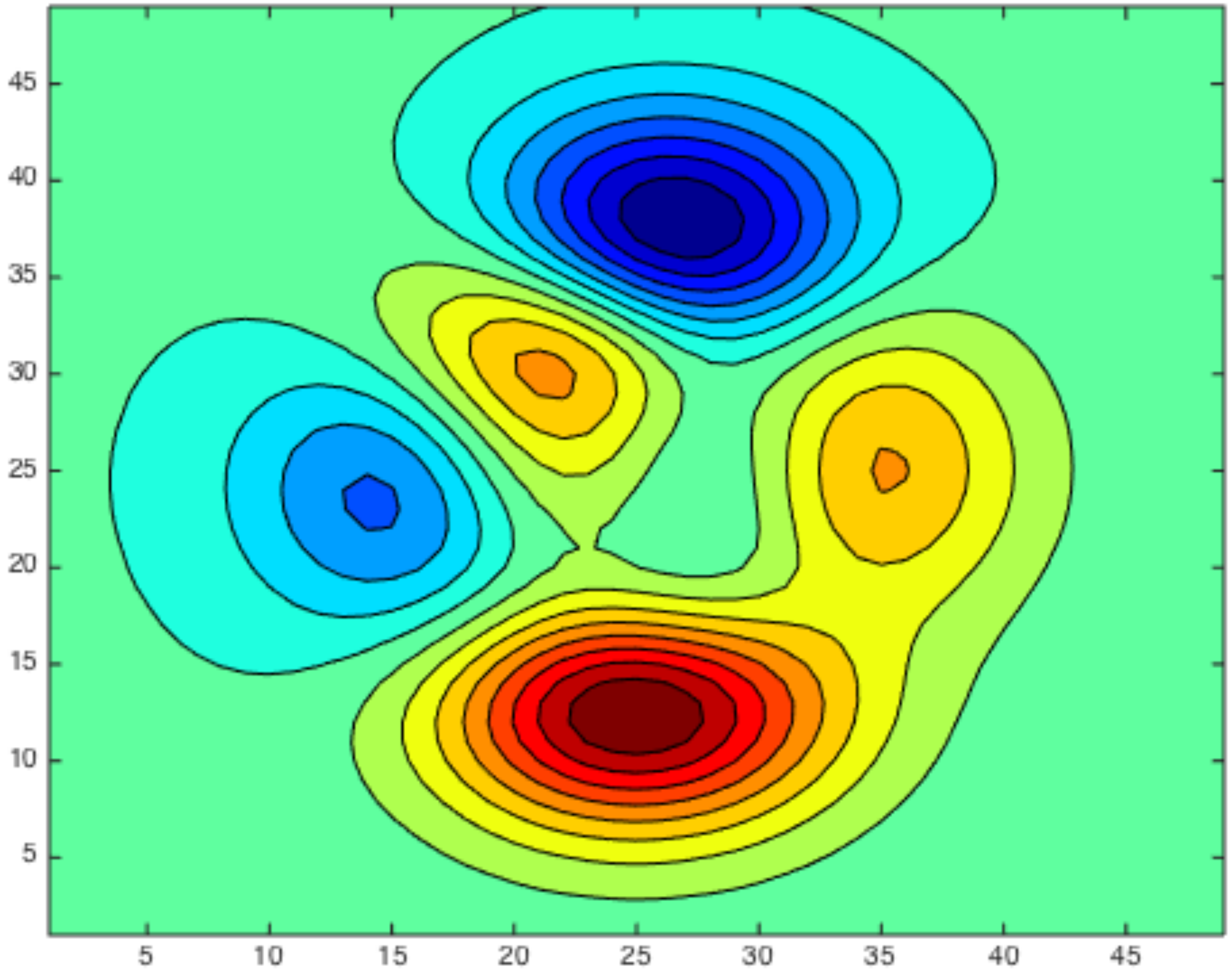
[Borland & Taylor, 2007]

Two-Hue Colormap



[Bergman et al., 1995]

"Get It Right in Black and White" - M. Stone



jet colormap

[S. Eddins (Matlab Blog), 2014]

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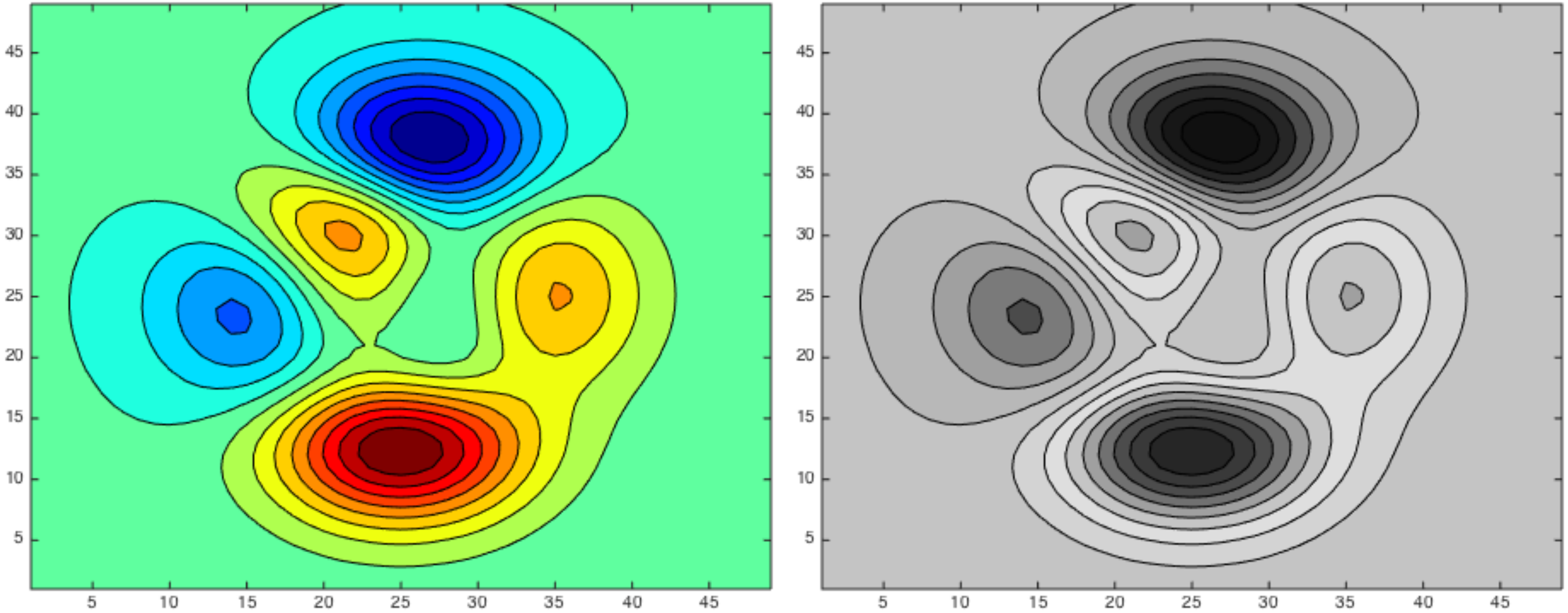

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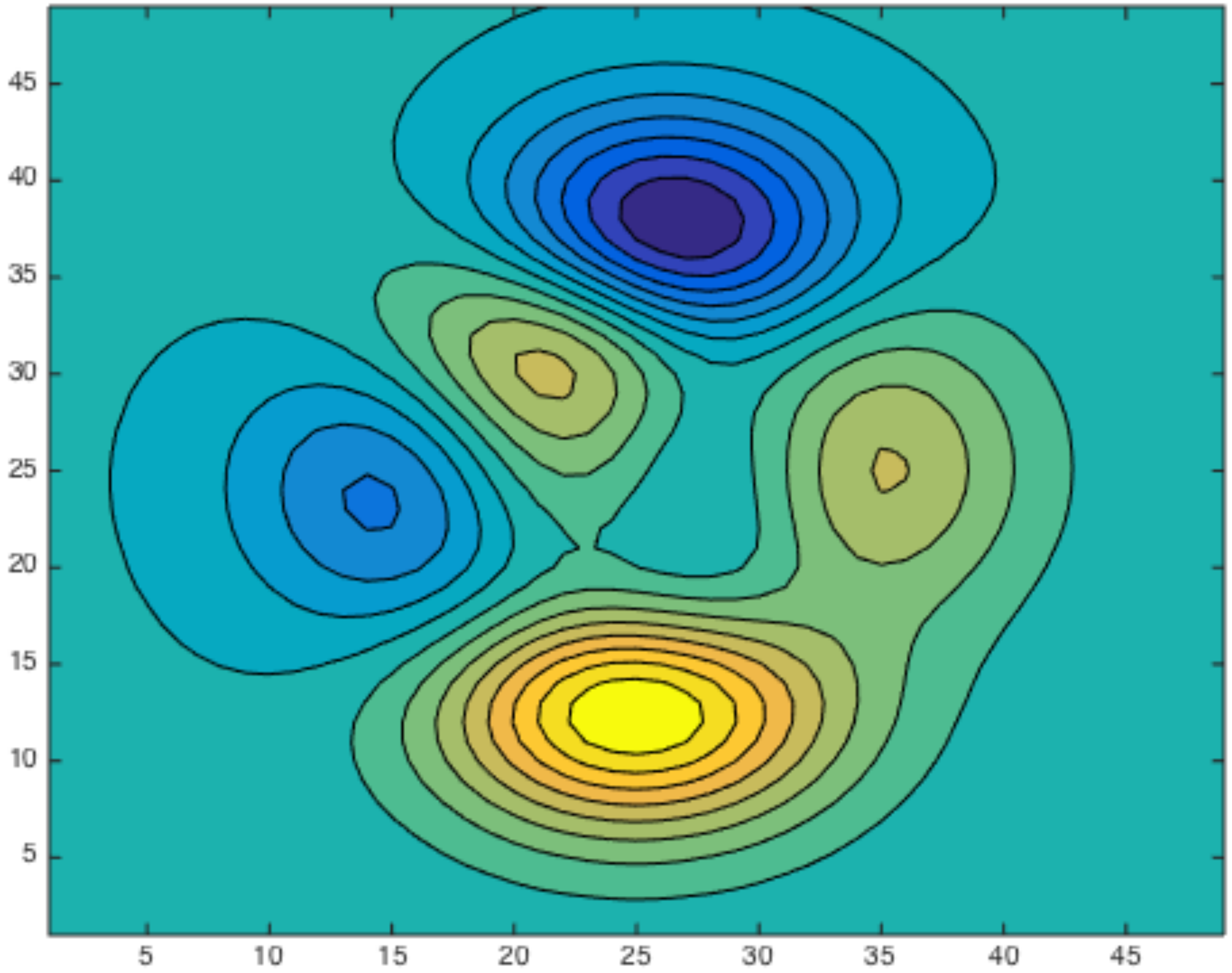

parula colormap

[S. Eddins (Matlab Blog), 2014]

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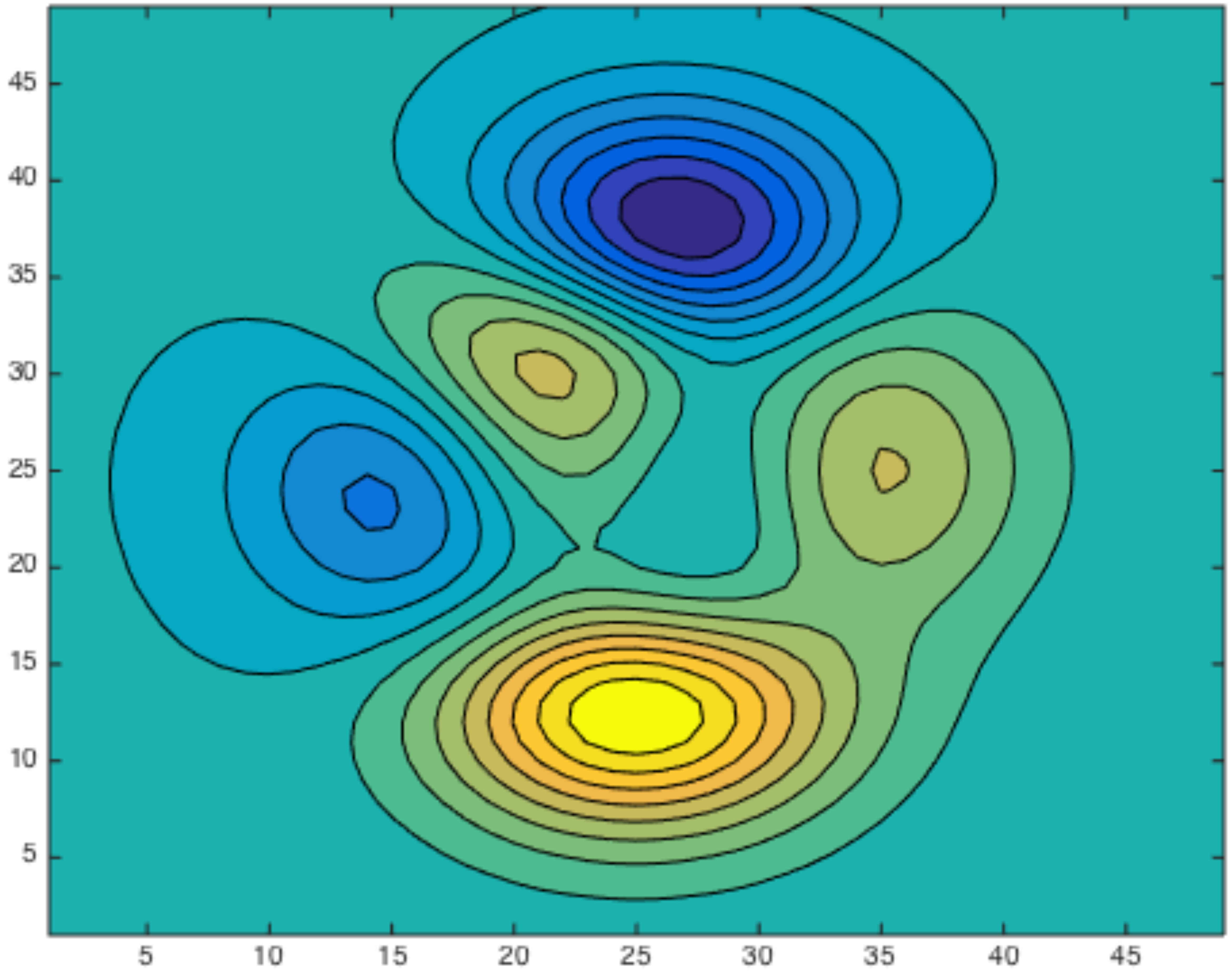
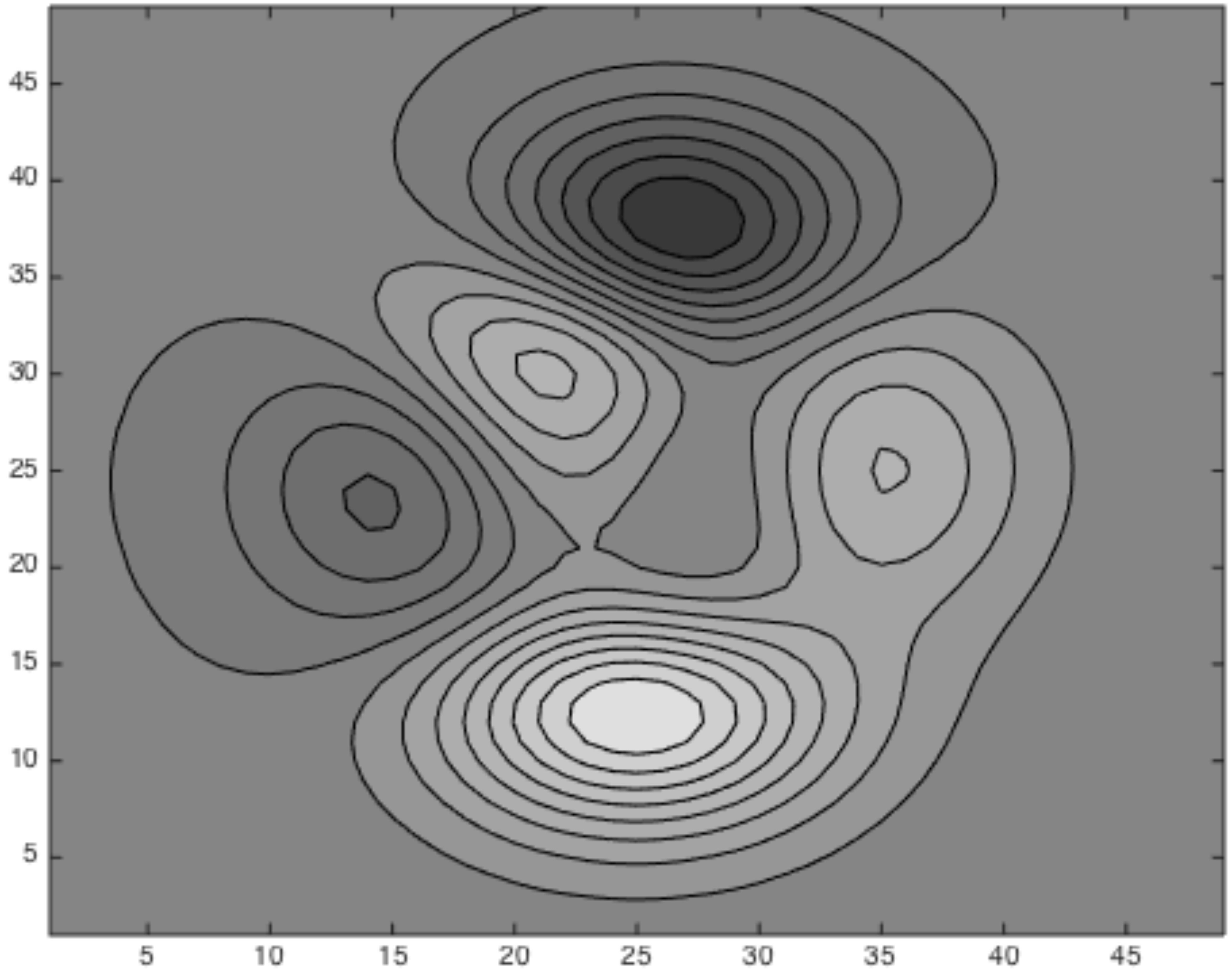




parula colormap

[S. Eddins (Matlab Blog), 2014]

Isoluminant Rainbow Colormap

Original

Isoluminant

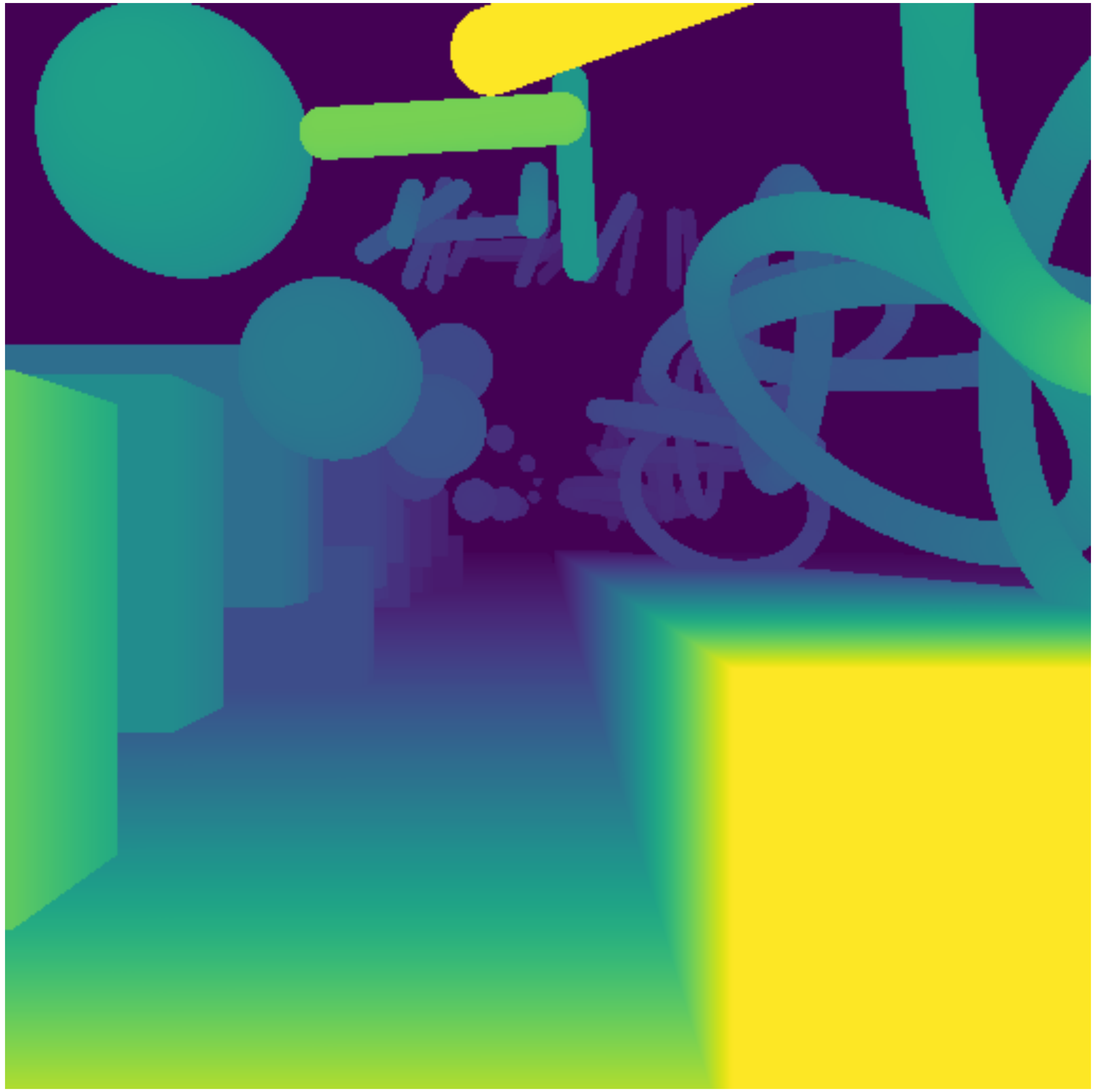
[Kindlmann et al., 2002]

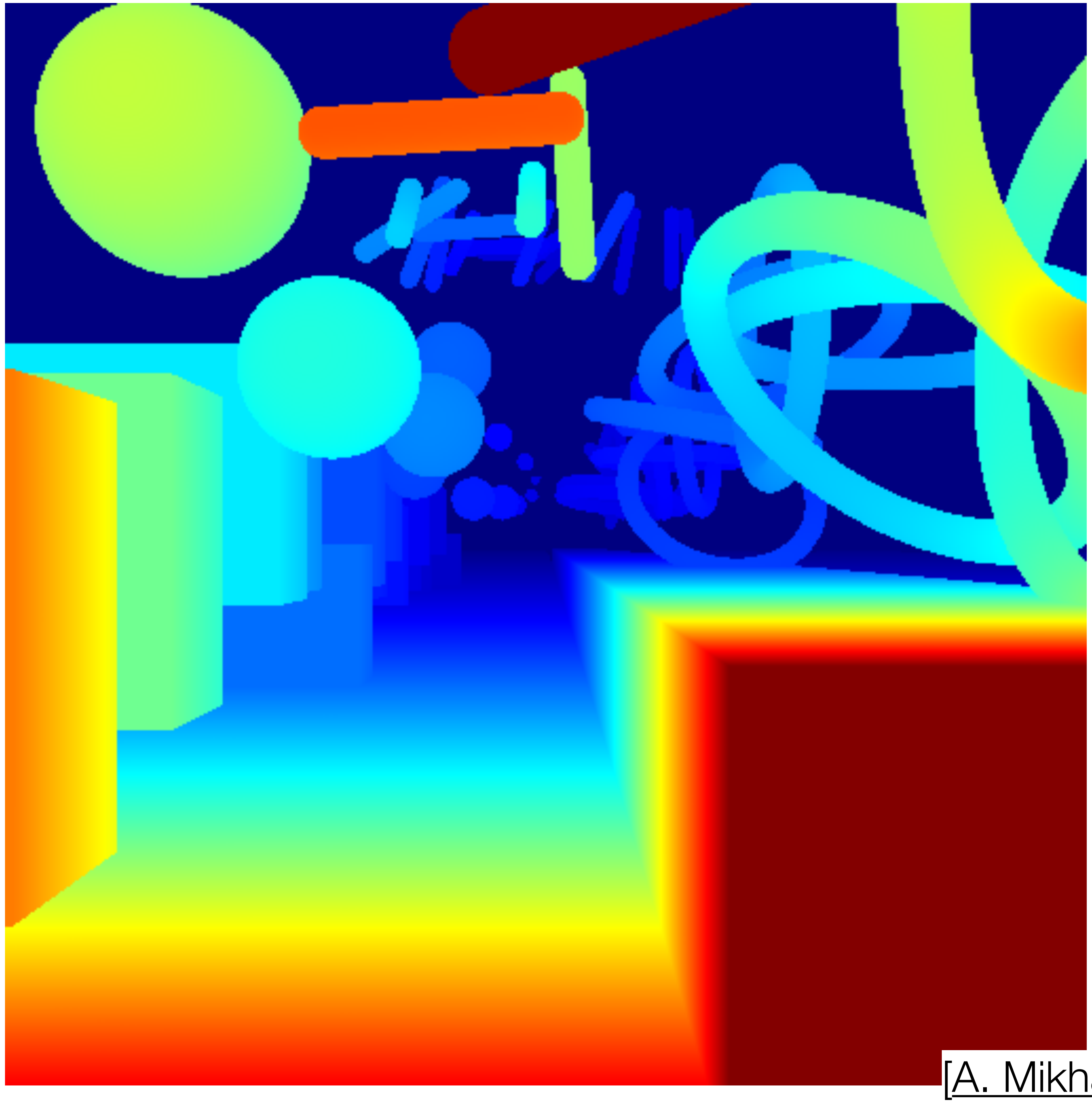
Turbo Colormap (August 2019)

Jet

Turbo

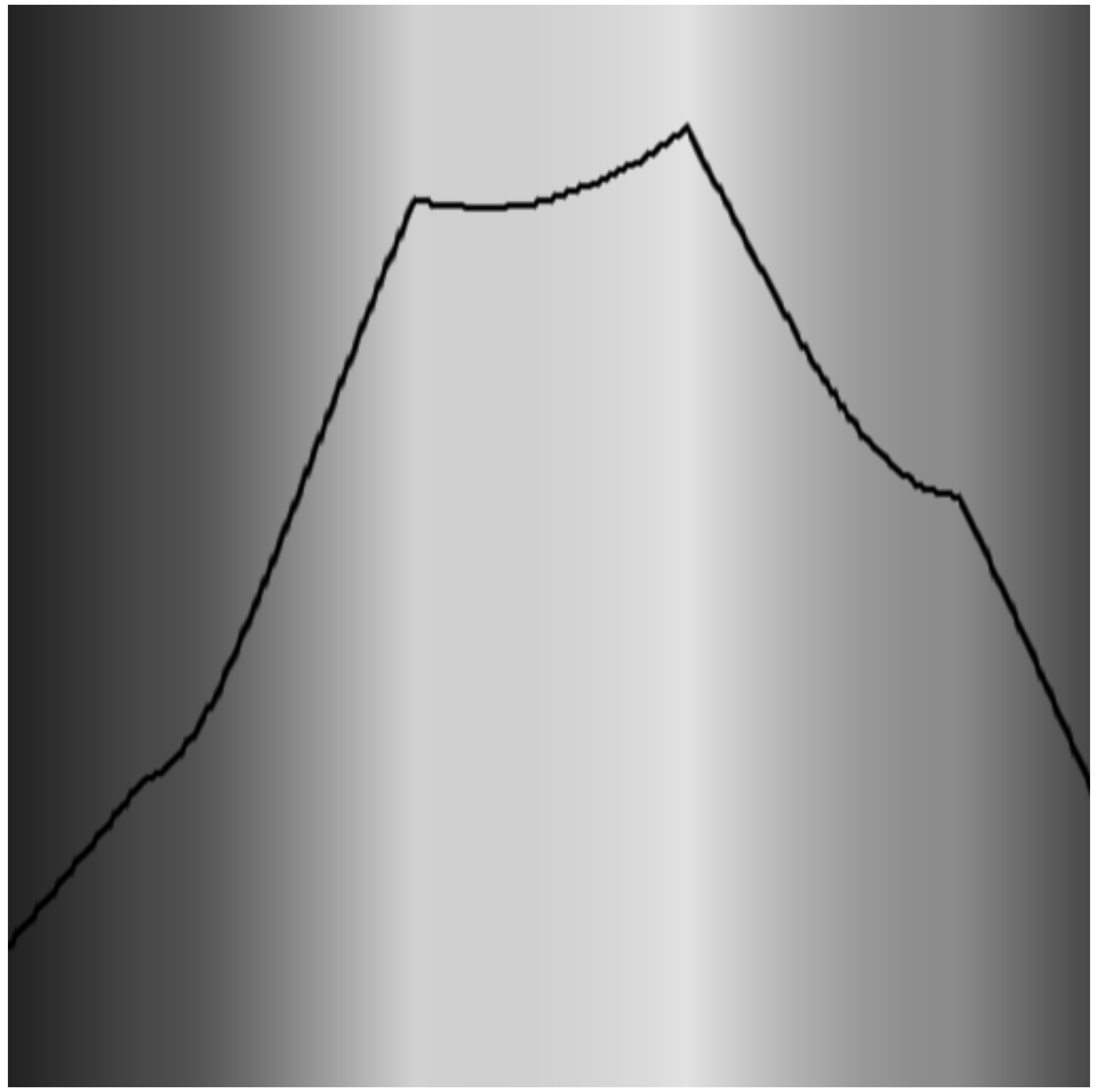
Turbo: More Detail in Disparity Maps?



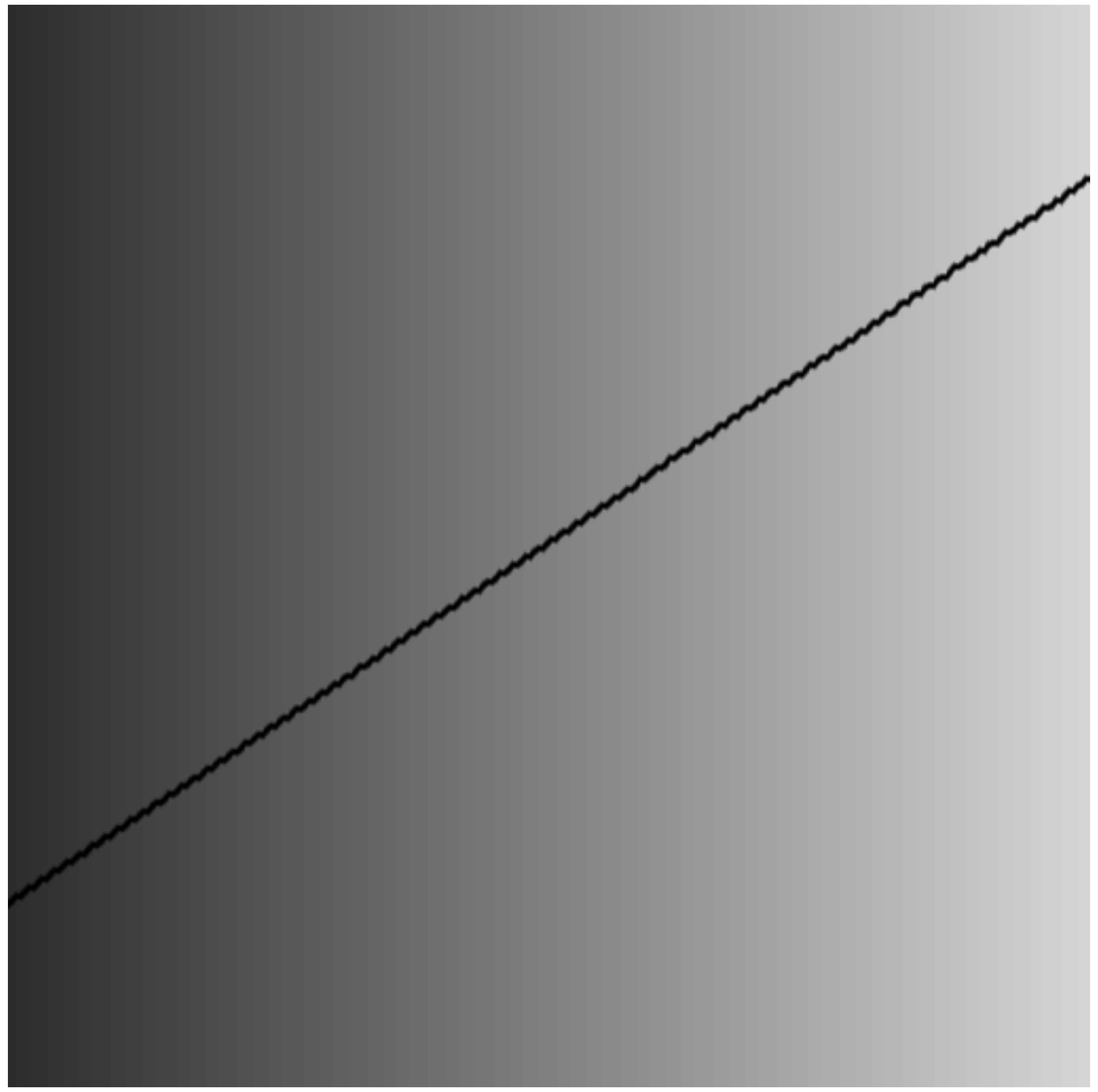


[A. Mikhailov]

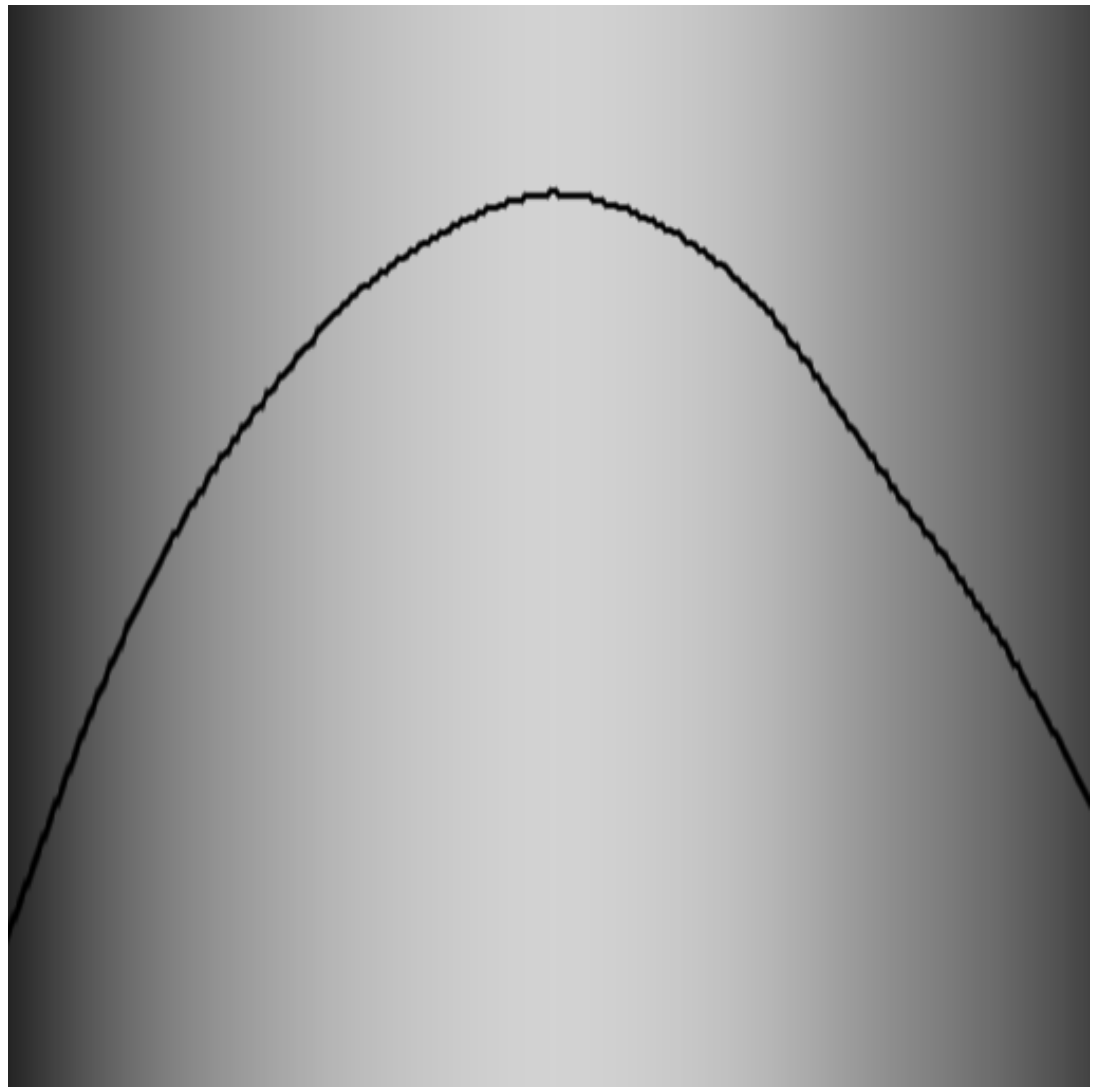
Turbo: Lightness Profiles



Jet



Viridis



Turbo

[A. Mikhailov]

Turbo Discussion

- Turbo is an improvement over jet
- Some fields (e.g. meteorology) have long used rainbow-like colormaps
- Argument is that segments are more easily located
- Turbo post claims that hue is prioritized in attention, but this seems to misinterpret the study…
- Brightness and saturation are more important than hue in attracting attention [Camgöz et al., 2004 h/t J. Stevens]

More Guidelines

- Nice set of articles by Lisa Charlotte Rost:
  - https://blog.datawrapper.de/colorguide/
  - https://blog.datawrapper.de/beautifulcolors/
- Her guidelines on choosing colors:
  1. **Copy from others**
  2. **Use Tools**
  3. …

Don't Dance Around the Color Wheel

NOT IDEAL

BETTER

[L. C. Rost]

Use Warm Colors & Blue

NOT IDEAL

BETTER

[L. C. Rost]

Avoid Too Little Contrast to Background

NOT IDEAL

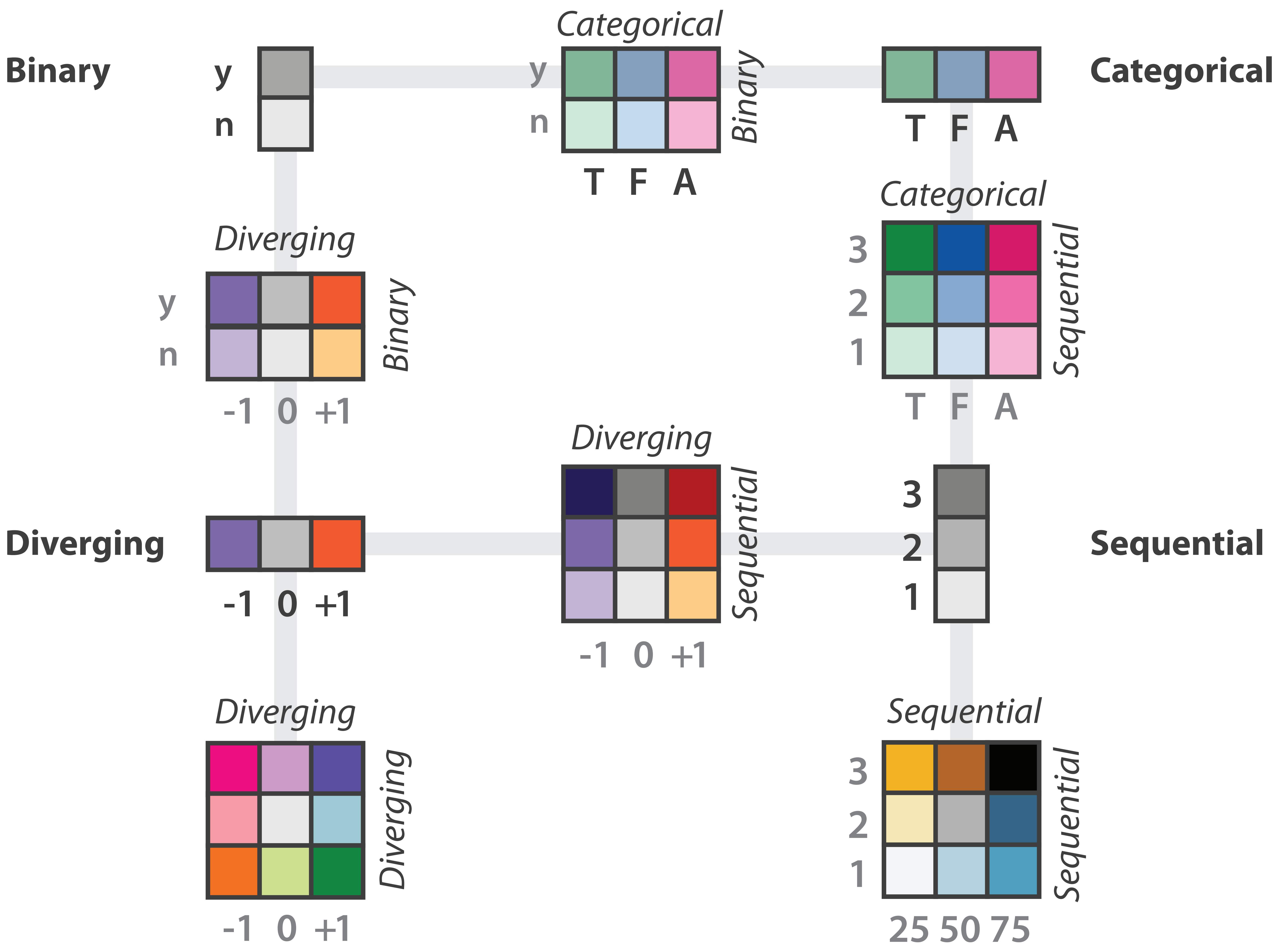
BETTER

[L. C. Rost]

D3's color scales

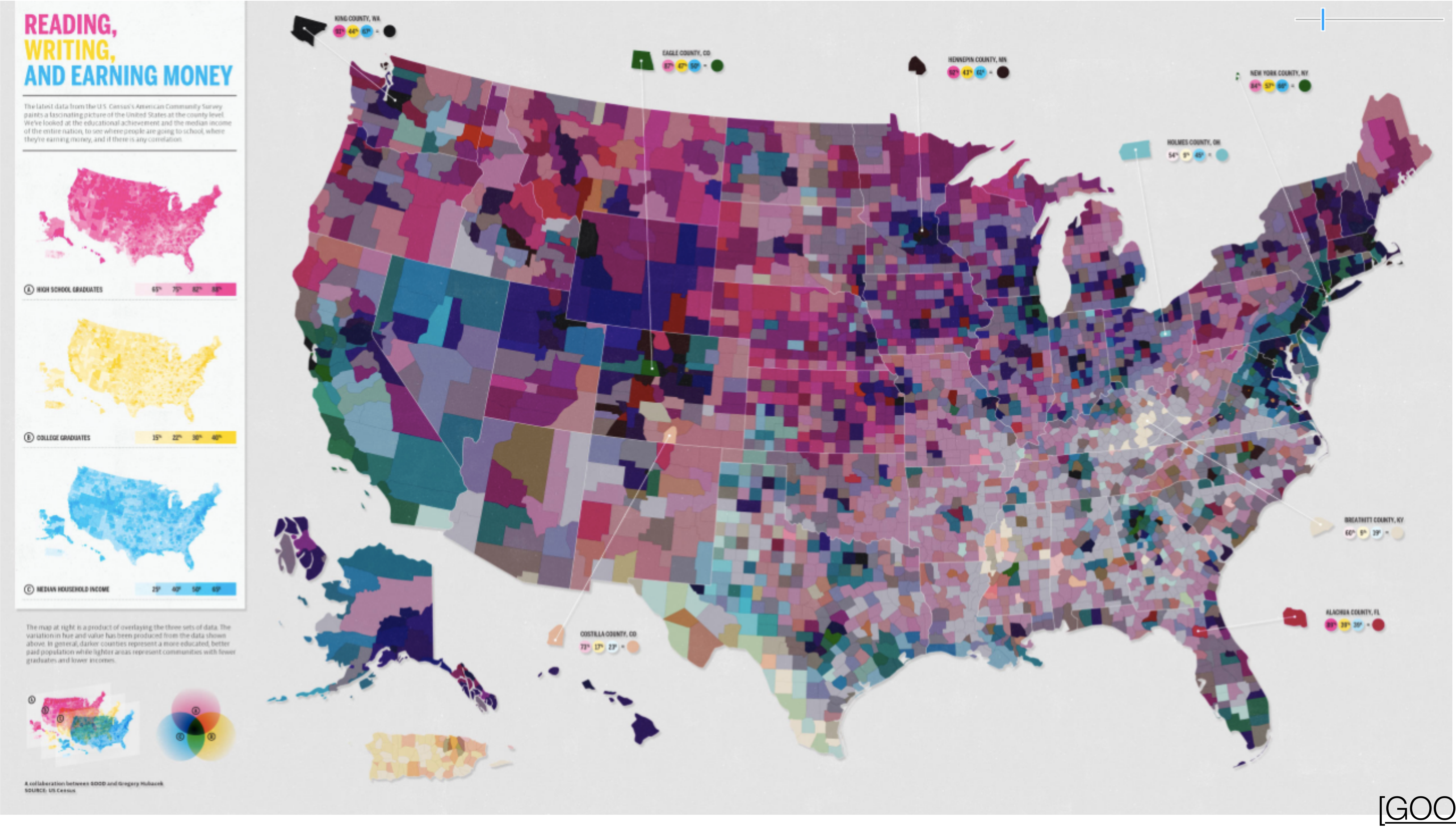
- https://github.com/d3/d3-scale-chromatic
- In v6, included in default bundle (no separate import)
- D3's built-in color scales
- Derived from ColorBrewer
- Sequential and diverging scales created using interpolation
- Hue **can** change, but be careful
- Color ramp [M. Bostock]

Bivariate Colormaps



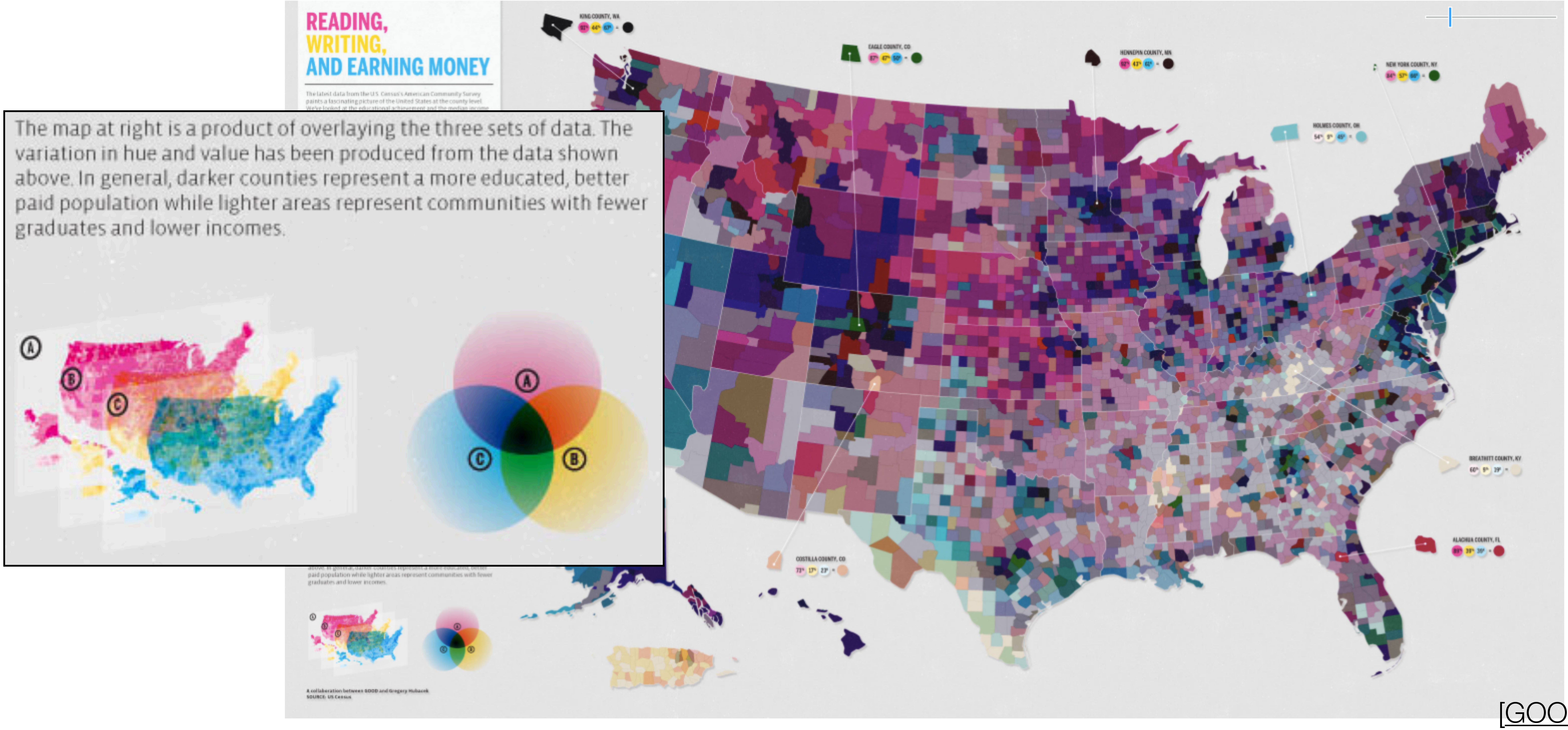
[Munzner (ill. Maguire), 2014]

Remember Separable vs. Integral



[GOOD]

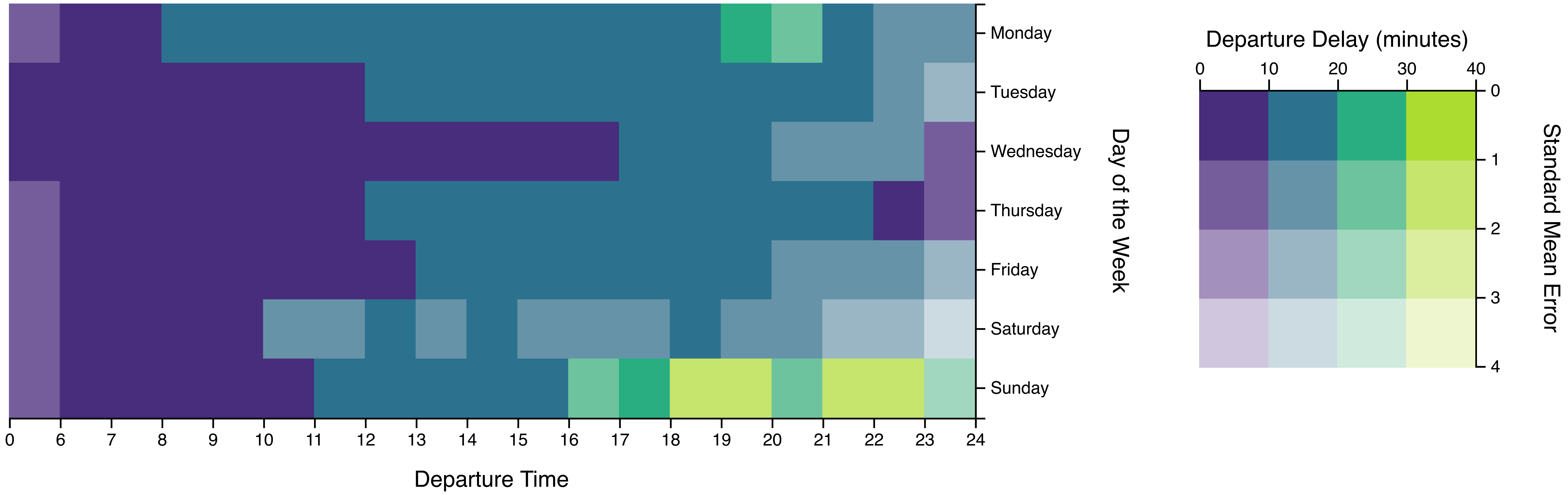
Remember Separable vs. Integral



[GOOD]

What about uncertain data?

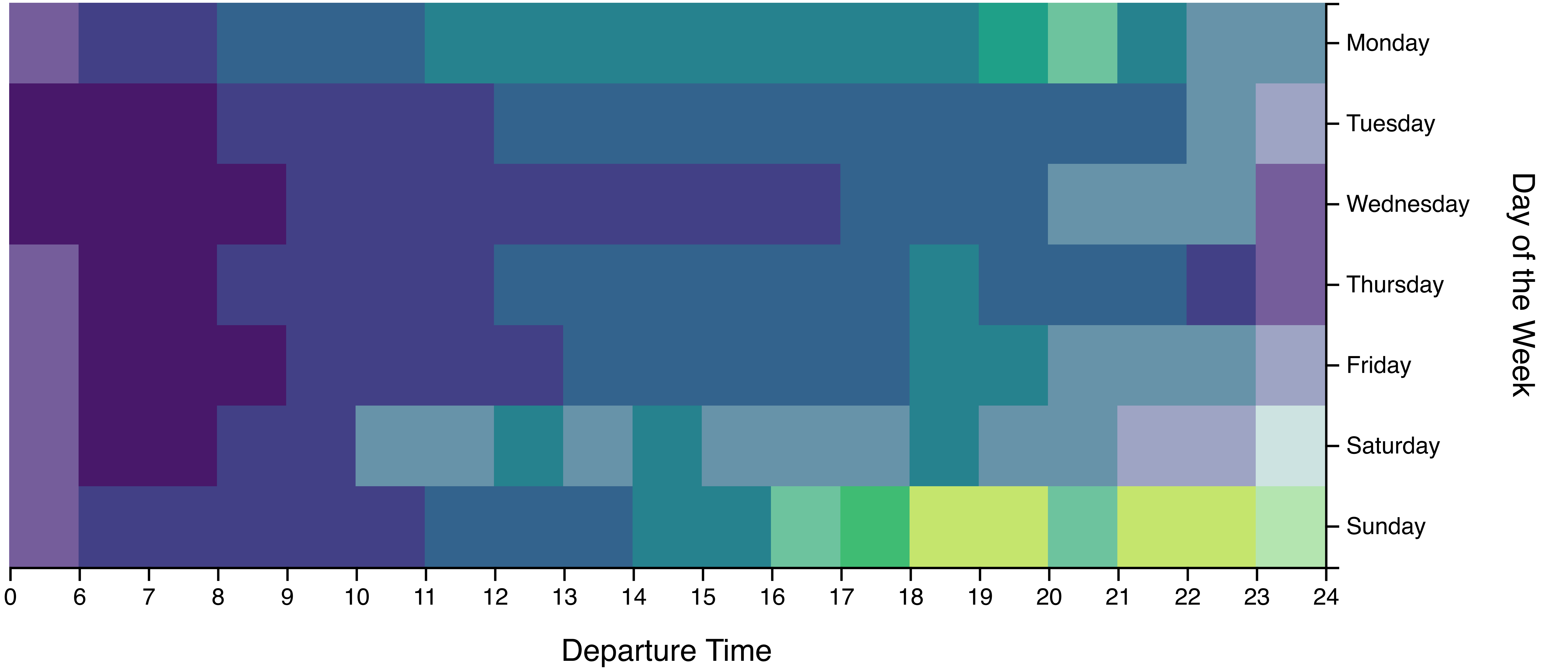
Bivariate Colormap (Uncertainty → Saturation)

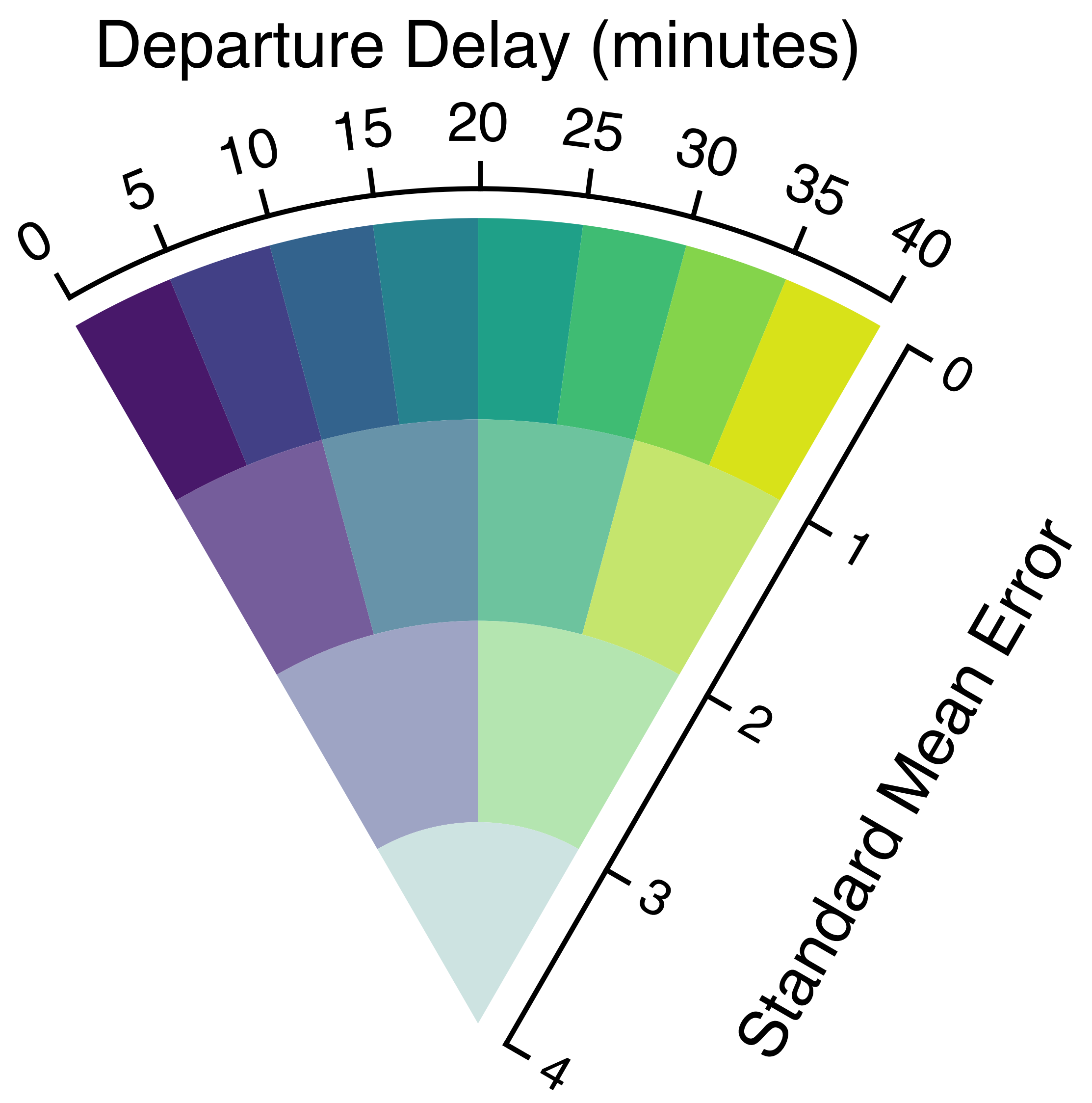


[Correll et al., 2018]

Value-Suppressing Uncertainty Palette (VSUP)

Same Channels, just binned differently





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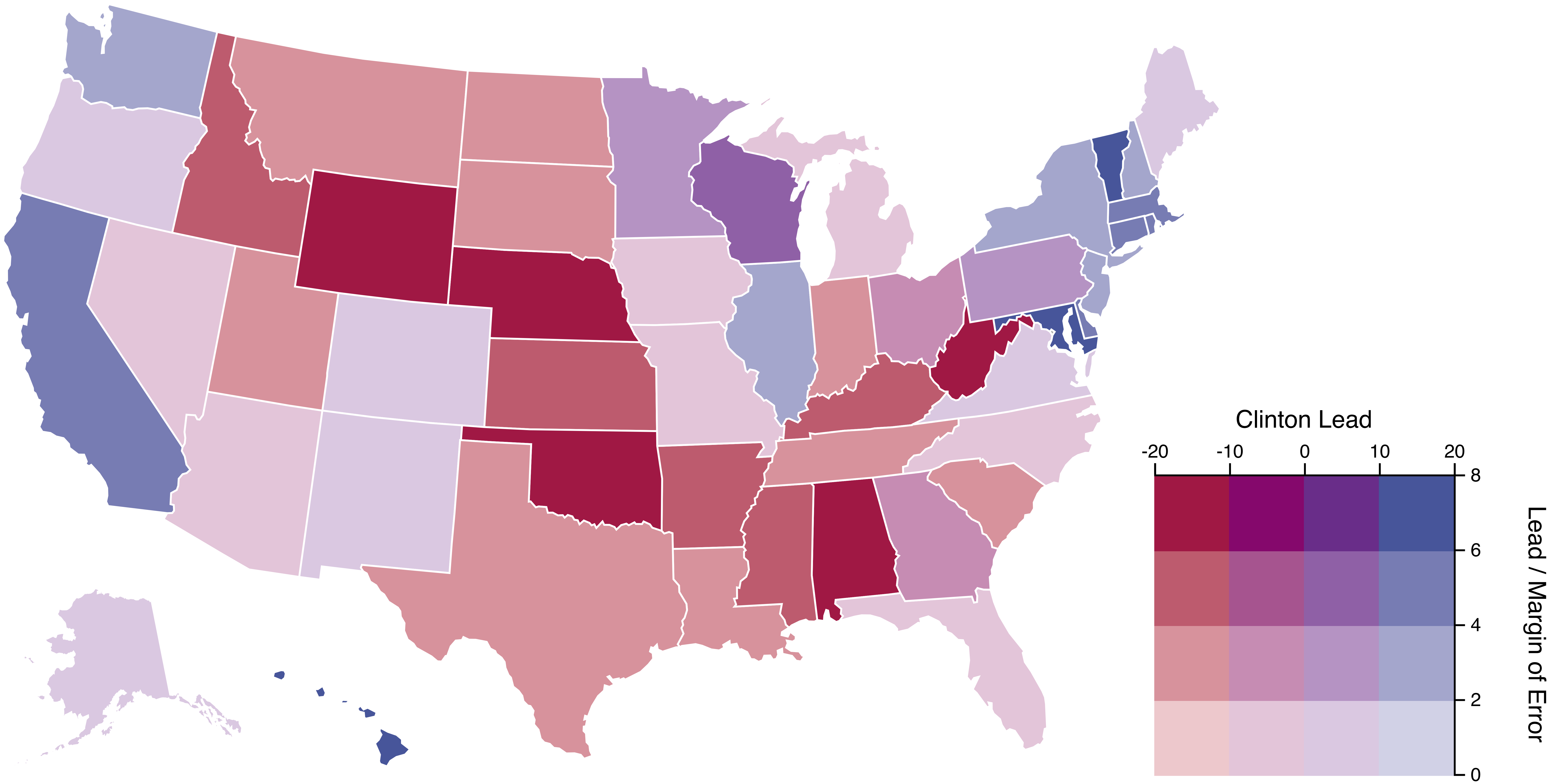
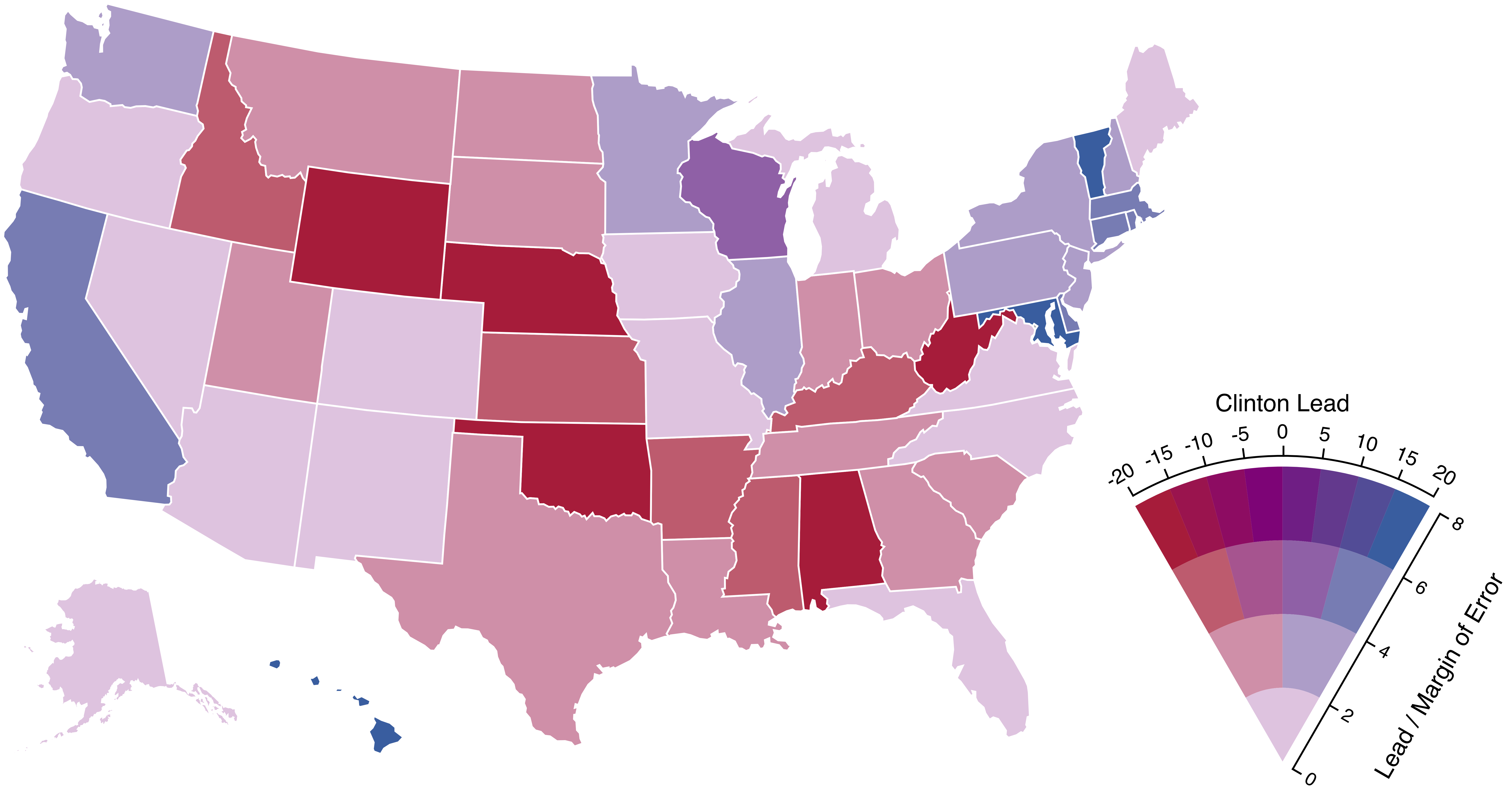


[Correll et al., 2018]

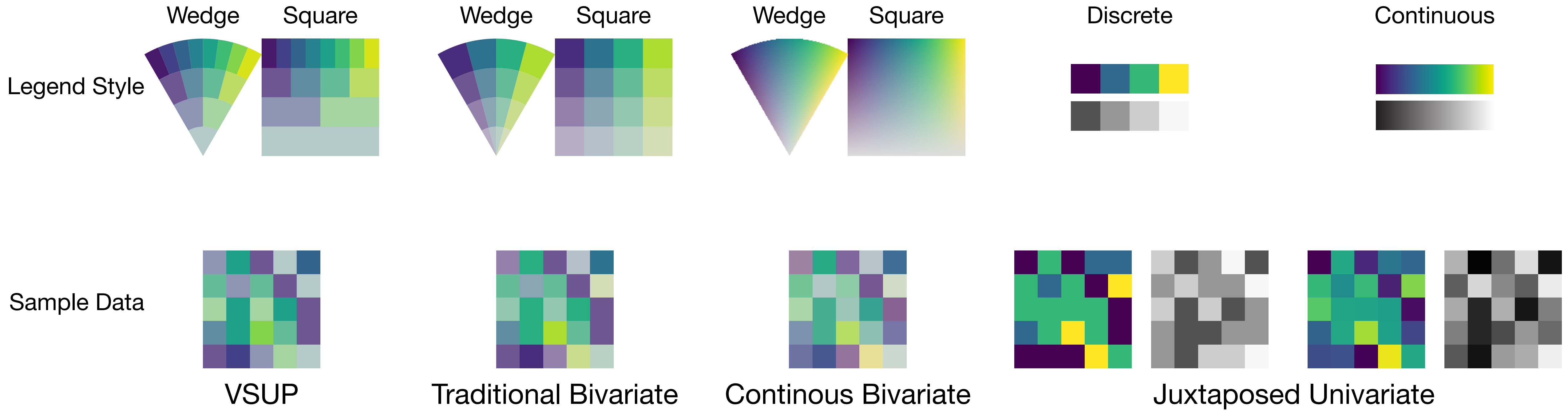
Value-Suppressing Uncertainty Palette



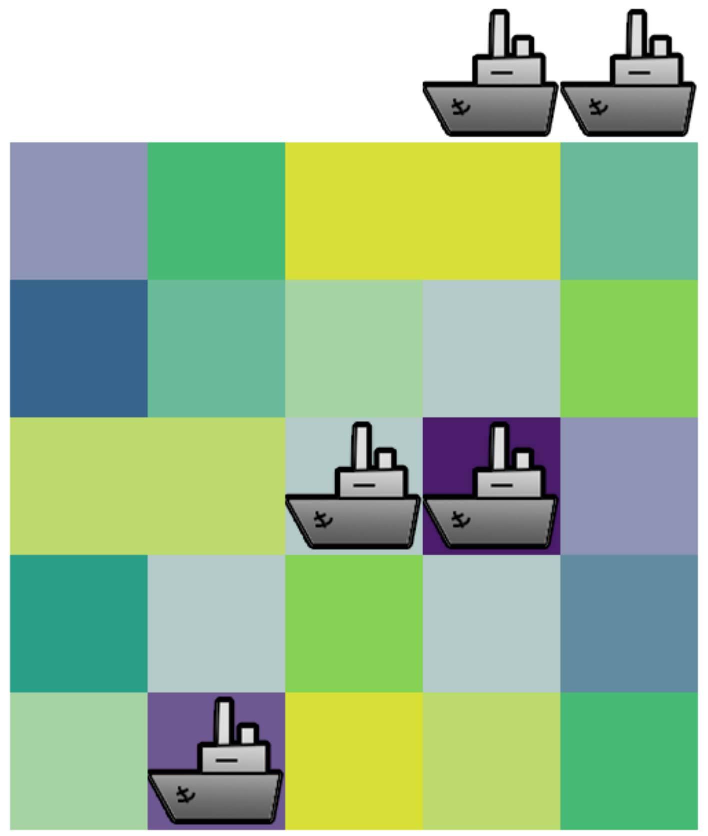
[Correll et al., 2018]

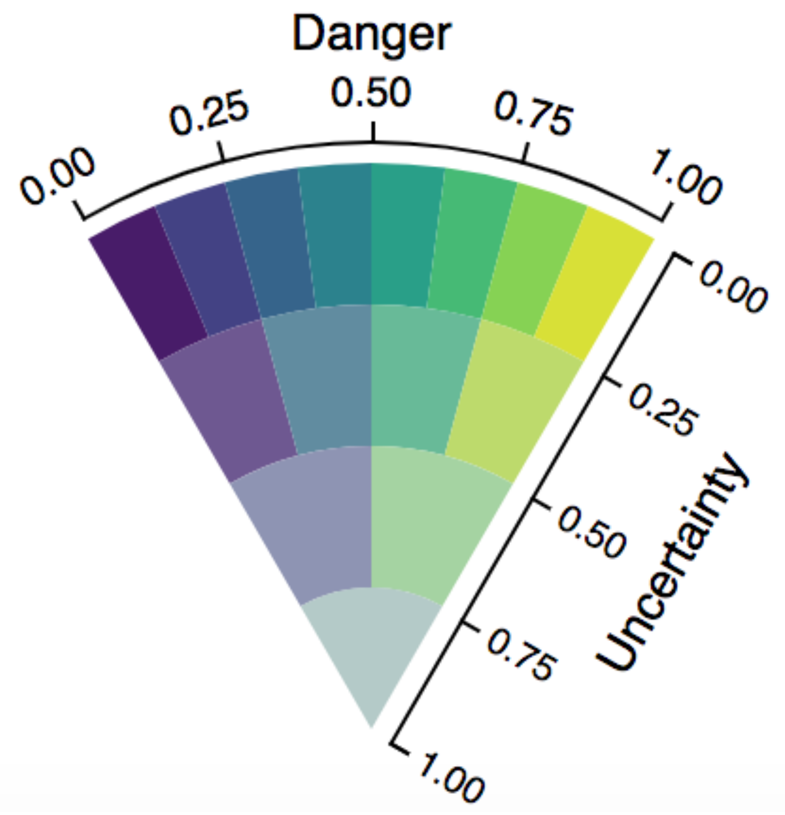
Evaluation

- Tasks:
  - Identification: locate spatial regions



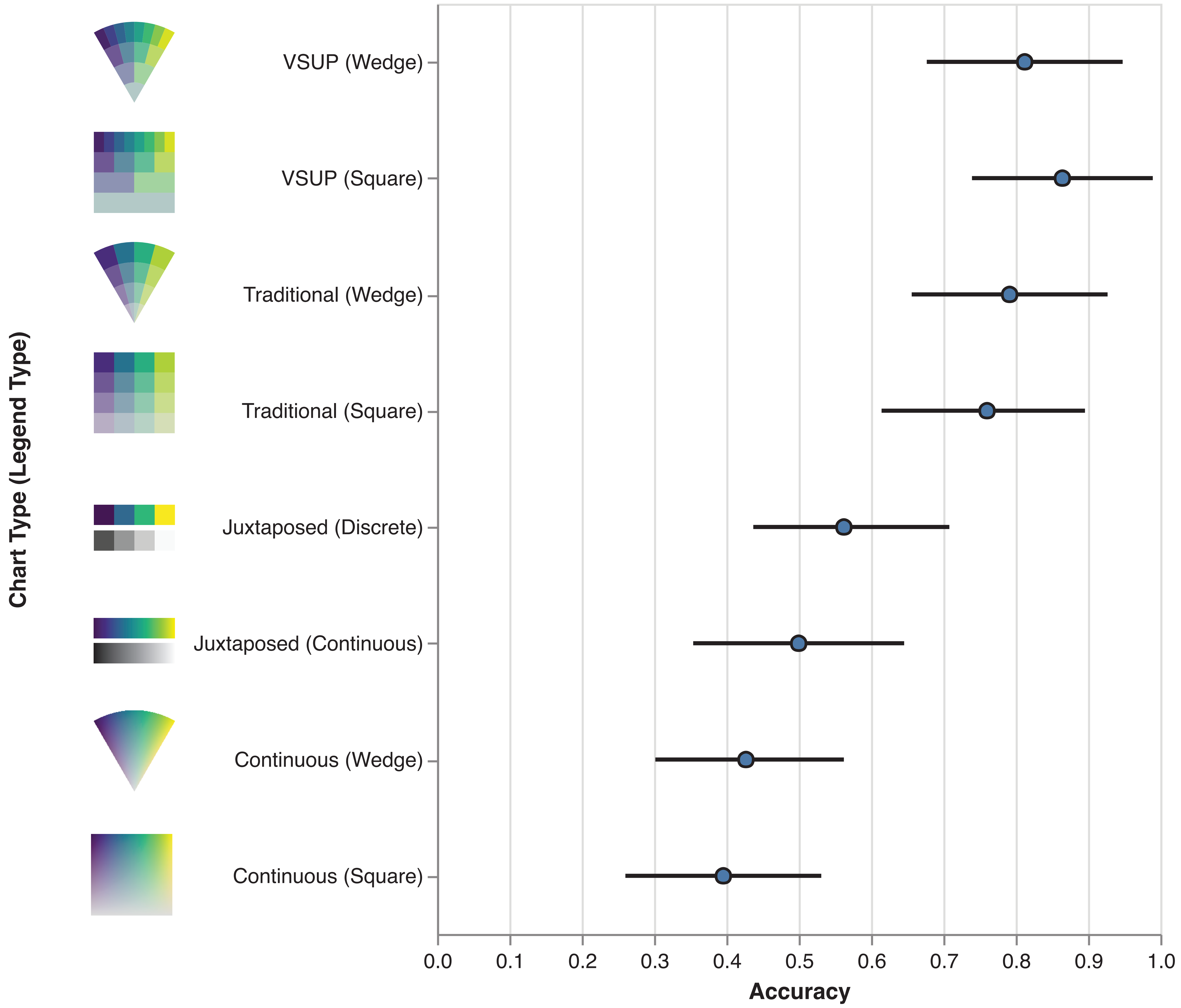
  - Prediction: place "safest locations"





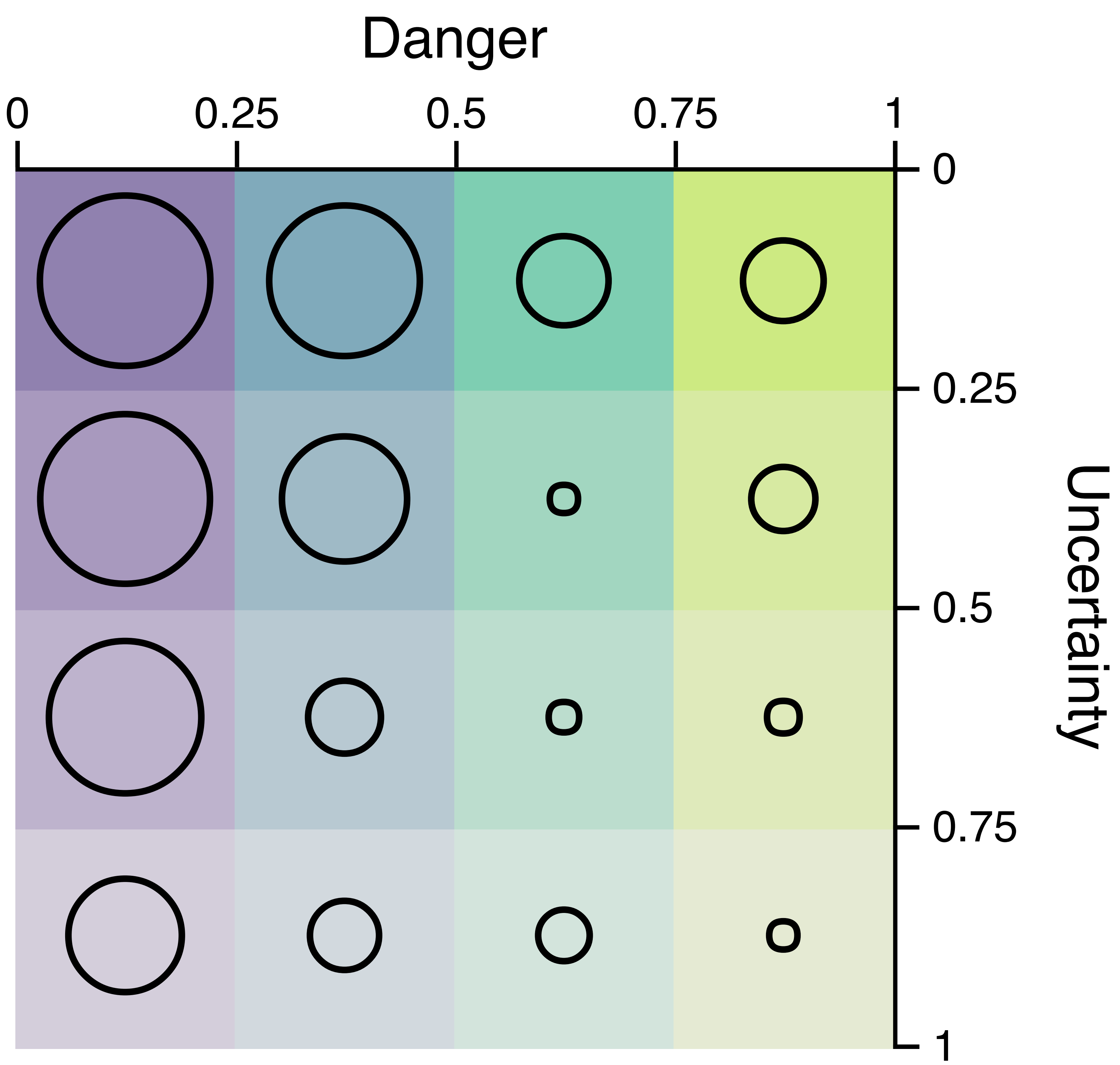
[Correll et al., 2018]

Identification Results

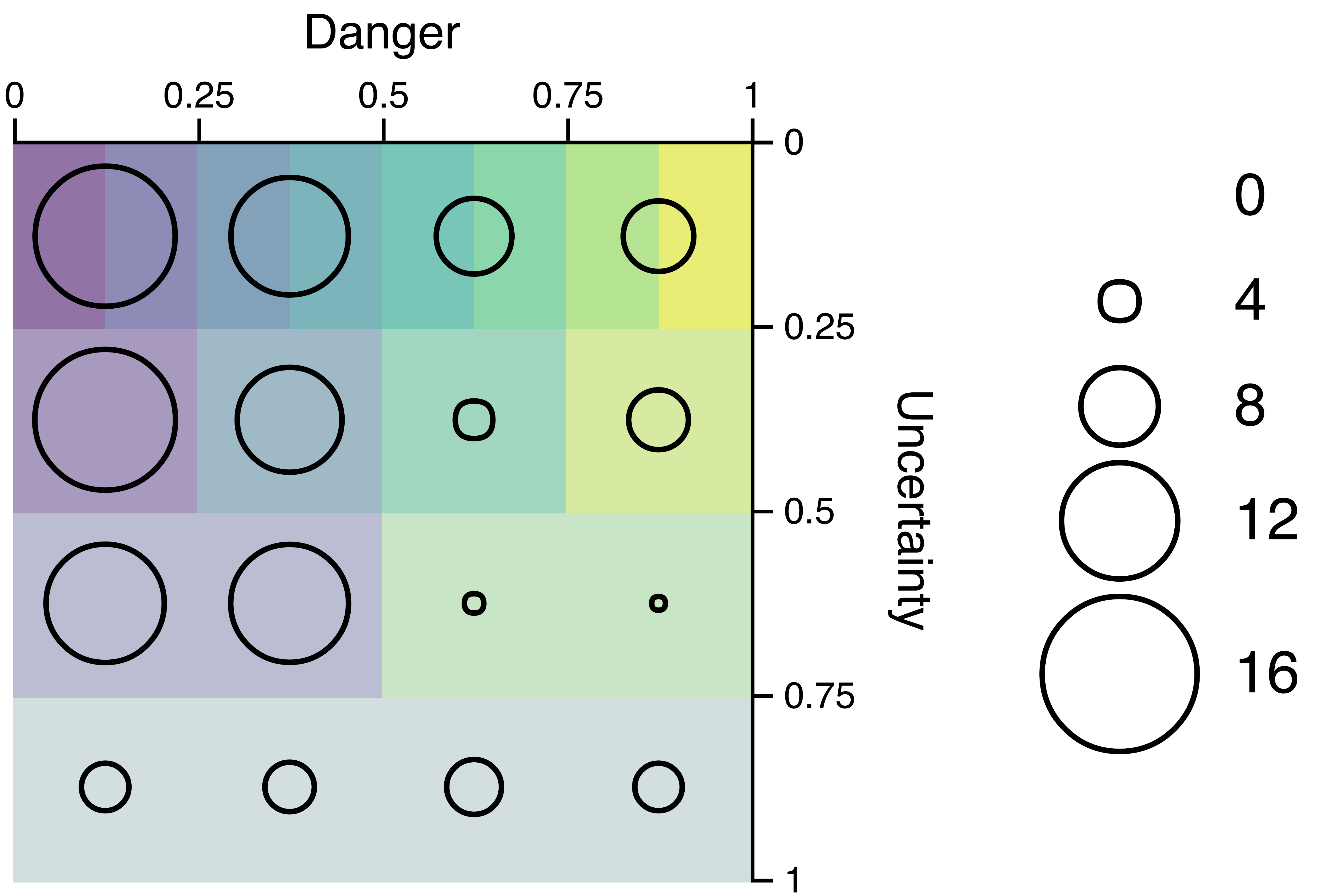


[Correll et al., 2018]

Prediction Results



Traditional Bivariate Map



VSUP

[Correll et al., 2018]

Results & Conclusions

- Legend shape has no significant effect
- Some indication that people avoid high uncertainty with VSUPs
- Tradeoff is that people do choose targets with higher danger when using a VSUP
- VSUPs present uncertainty information **simultaneously** (superimposed) instead of juxtaposed
- VSUPs encode value and uncertainty via **discrete, quantized bins** instead of continuously

[Correll et al., 2018]